

Indirect influence in social networks as an induced percolation phenomenon

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Percolation theory has been widely used to study phase transitions in network systems. It has also successfully explained various macroscopic spreading phenomena across different fields. Yet, the theoretical frameworks have been focusing on direct interactions among nodes, while recent empirical observations have shown that indirect interactions are common in many network systems like social and ecological networks, among others. By investigating the detailed mechanism of both direct and indirect influence on scientific collaboration networks, here we show that indirect influence can play the dominant role in behavioral influence. To address the lack of theoretical understanding of such indirect influence on the macroscopic behavior of the system, we propose a percolation mechanism of indirect interactions called induced percolation. Surprisingly, our model exhibits a unique anisotropy property. Specifically, directed networks show first-order abrupt transitions as opposed to the second-order continuous transition in the same network structure but with undirected links. A mix of directed and undirected links leads to rich hybrid phase transitions. Furthermore, a unique feature of the nonmonotonic pattern is observed in network connectivities near the critical point. We also present an analytical framework to characterize the proposed induced percolation, paving the way to further understanding network dynamics with indirect interactions.

percolation | indirect interactions | social network | phase transition | behavioral contagion

Percolation theory (1) is one of the most prominent frameworks within statistical physics. Initially developed (2, 3) to explain the chemical formation of large macromolecules, it has been recently used to study various dynamical processes in complex networks (4–9). Examples include the use of bond percolation (9, 10) to study the wide spread of rumors over online social media and outbreaks of infectious diseases on structured populations. Site percolation (4, 5, 11) has been employed to study the cascading failures of infrastructure networks (6, 12–16) and the resilience of protein–protein interaction networks (17). Likewise, bootstrap percolation (18), k -core (19–21), and linear threshold percolation (7, 22–24) have enabled the study of the spreading of behaviors over social networks. Finally, the so-called explosive percolation (25) has allowed a better characterization of systems' structural transitions when they are growing or can adapt, whereas core percolation (26, 27) has contributed significantly to insights into nondeterministic polynomial problems. Common to all these percolation models is that they have successfully described various important dynamical phenomena by considering different direct interactions (8, 9, 28) among network nodes; in particular, they have captured the behavior of network systems as given by phase transitions (4, 8, 9, 28, 29).

Our study is motivated by recent evidence that there are many systems in which indirect interactions play a major role in their spreading dynamics (30–35). Such underlying indirect interactions have important implications not only on the dynamics of the system but also on the evolution and the emergence of network structures. For example, Christakis and Fowler (30, 31) found that for the spreading of many social behaviors, such as drug (36) and alcohol addictions (37) and obesity (30), an individual can span their influence to their friends around three degrees of separation (friend of a friend's friend). This phenomenon is also widely known as “three degrees of influence” in social science. In ecological networks, Guimarães et al. (32, 33) discovered in 2017 that indirect effects contribute strongly to the trait coevolution among reciprocal species, which can alter environmental selection and promote the evolution of species.

Despite the ubiquity of indirect influence in various real-world systems, few studies have examined the exact mechanisms by which the indirect influences occur, or the relative strengths between direct and indirect influences. Here, based on empirical

Significance

Increasing empirical evidence in diverse social and ecological systems has shown that indirect interactions play a pivotal role in shaping systems' dynamical behavior. Our empirical study on collaboration networks of scientists further reveals that an indirect effect can dominate over direct influence in behavioral spreading. However, almost all models in existence focus on direct interactions, and the general impact of indirect interactions has not been studied. We propose a new percolation process, termed induced percolation, to characterize indirect interactions and find that indirect interactions raise a plethora of new phenomena, including the wide range of possible phase transitions. Such an indirect mechanism leads to very different spreading outcomes from that of direct influences.

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Table 1. Description of bibliographic datasets used in the empirical studies

Established field (PACS)	Emerging field (PACS)	No. of authors	No. of edges	Constructing network period	Field emerging period	Observation period
Chaos (05.45)	Complex networks (89.75)	1,833	3,128	1999–2003	2001–2003	2004–2006
Phase transitions (64.60)	Complex networks (89.75)	1,265	2,864			
EPLDS (73.20)	OPLDS (78.67)	2,069	5,900			
Carbon nanotubes (39).	Graphene (39).	20,011	110,041	2009–2013	2011–2013	2014–2016

The first and second columns are names and Physics and Astronomy Classification Scheme (PACS) numbers (except carbon nanotubes and graphene) for the four pairs of research fields. The third to fifth columns are the number of authors and edges and the period used to construct collaboration networks, respectively. The sixth column is the period during which a new field emerges and “focused” scientists are specified. The seventh column is the period to observe scientists’ behavioral change and to calculate the indicator Q_i .

analyses of scientific collaboration networks, we reveal that indirect influence occurs through next-nearest neighbors and can be the dominant mechanism through which research interests change; on the contrary, evidence of direct (nearest) influence is relatively weak.

However, on the theoretical front, up to now there has been no percolation-based theoretical model to describe the underlying mechanism of indirect influence or its distinctions with existing percolation models in terms of the macroscopic behaviors. For either regular networks or complex networks, various percolation models like bond, site, bootstrap, k -core, linear threshold and core, etc., are always based on direct interactions (8, 9, 28) among nodes. In essence, all of these models only take into account the existence and the strength of directly connected nodes, regardless of any indirect influences of other nodes. Hence, they are not suitable for describing the indirect mechanism. Here, we propose a percolation framework called induced percolation to theoretically study the impact of such an indirect mechanism on the whole system.

Our results show that indirect interactions lead to a unique macroscopic behavior characterized by anisotropy and phase transitions and different spreading outcomes compared to the direct influence mechanisms. Specifically, we study the most general scenario in which links can have directions and report that varying the links’ directionality could change the order of the phase transition. This is in sharp contrast to previous percolation models, for which the nature of the phase transitions is not affected by the directionality of links. Such rich phase transition behavior is further illustrated in our simulations on empirical networks. To the best of our knowledge, the phenomenon of directionality-related order of the phase transitions only exists in some special cases of core percolation (27), whereas it is shown to be a generic feature in our indirect interaction model.

Results

Empirical Indirect Influence Mechanisms. To investigate the exact mechanism of neighboring influence and its direct/indirect nature in empirical networks, we study collaboration networks of scientists. Here the “behavior” is meant as the research field(s) of a scientist, and the “spreading of behavior” is defined as the propensity of the scientist to stay in his/her established field or shift to an emerging field. We then study how scientists’ research fields are influenced by their direct (nearest) neighbors and indirect (next-nearest) neighbors. We choose four pairs of fields in physics that have large numbers of scientists involved: chaos vs. complex networks, phase transitions vs. complex networks, electrical properties of low-dimensional structures vs. optical properties of low-dimensional structures (hereinafter referred to as EPLDS vs. OPLDS), and carbon nanotubes vs. graphene. For each pair of fields, the latter field is the emerging field (new field) that attracts scientists from the former (old, already established) field.

Specifically, we analyze the datasets of articles published by the American Physical Society (APS) (38) and Web of Science (39), considered as representative data sources for the studied fields (we share all the data of this study at <https://github.com/Jia-Rong-Xie>). Based on articles in each pair of fields, covering in total 5 y around the emergence of a new field (see Table 1 and *SI Appendix, Fig. S1*), we construct a collaboration network. The nodes are the scientists, and a link is established between any pair of scientists who have at least one joint publication. Scientists who have published multiple articles (at least two in APS and five in Web of Science dataset; refer to extended discussion for parameter robustness in *SI Appendix, Figs. S7–S13*) in the old field yet have not published any articles in the new field are defined as focused scientists in the old field. They are assumed to be the influencers in the networks and labeled as state 1. For any other nodes (influenced) in the networks, we calculate the number of direct and indirect “influencers” for each node. The number of direct influencers of node i is simply the number of its nearest neighbors with state 1, and we denote it as \tilde{k}_i . For the number of indirect influencers of node i , we first identify its state 1 neighbors. For each of the direct influencers (direct state 1 neighbors), we then count the number of their own state 1 neighbors, and the maximum count is defined as the number of indirect influencers m_i (also called induced index). On each of the direct influencers of node i , we further count its degree and define the maximum degree of them as degree index d_i . A visual illustration of the definitions is shown in Fig. 1A.

Within the next 3 y (see Table 1 and *SI Appendix, Fig. S1*), we count each influenced i ’s publications and calculate the proportion Q_i of articles in the old field by the following expression:

$$Q_i = \frac{P_i^{\text{old}}}{P_i}, \quad [1]$$

where P_i^{old} and P_i represent the number of papers in the old field and the total number of papers published by scientist i during the observation period, respectively. A higher Q_i value of the influenced i then indicates that it receives more influence by the “influencers” with state 1, either directly or indirectly. Our results in Fig. 1B, C, and E (and *SI Appendix, Figs. S4–S6*) clearly show that Q_i increases with the indirect influence index m_i , yet not so much with direct influence index \tilde{k}_i (also called k -core index; see Fig. 1C and D) or the degree index d_i (see Fig. 1E and F) and the second-nearest degree index κ_i (see *SI Appendix, Fig. S6*). This indicates that rather than direct influence, indirect influence plays a dominant role in the choice of research focus among scientists. Indeed, we find that nodes i and h , via node j (see Fig. 1A), are more likely to coauthor publications in the old field, which means that the quantitative correlation between Q_i and m_i does mediate the collaboration relationship (see *SI Appendix, Fig. S14*).

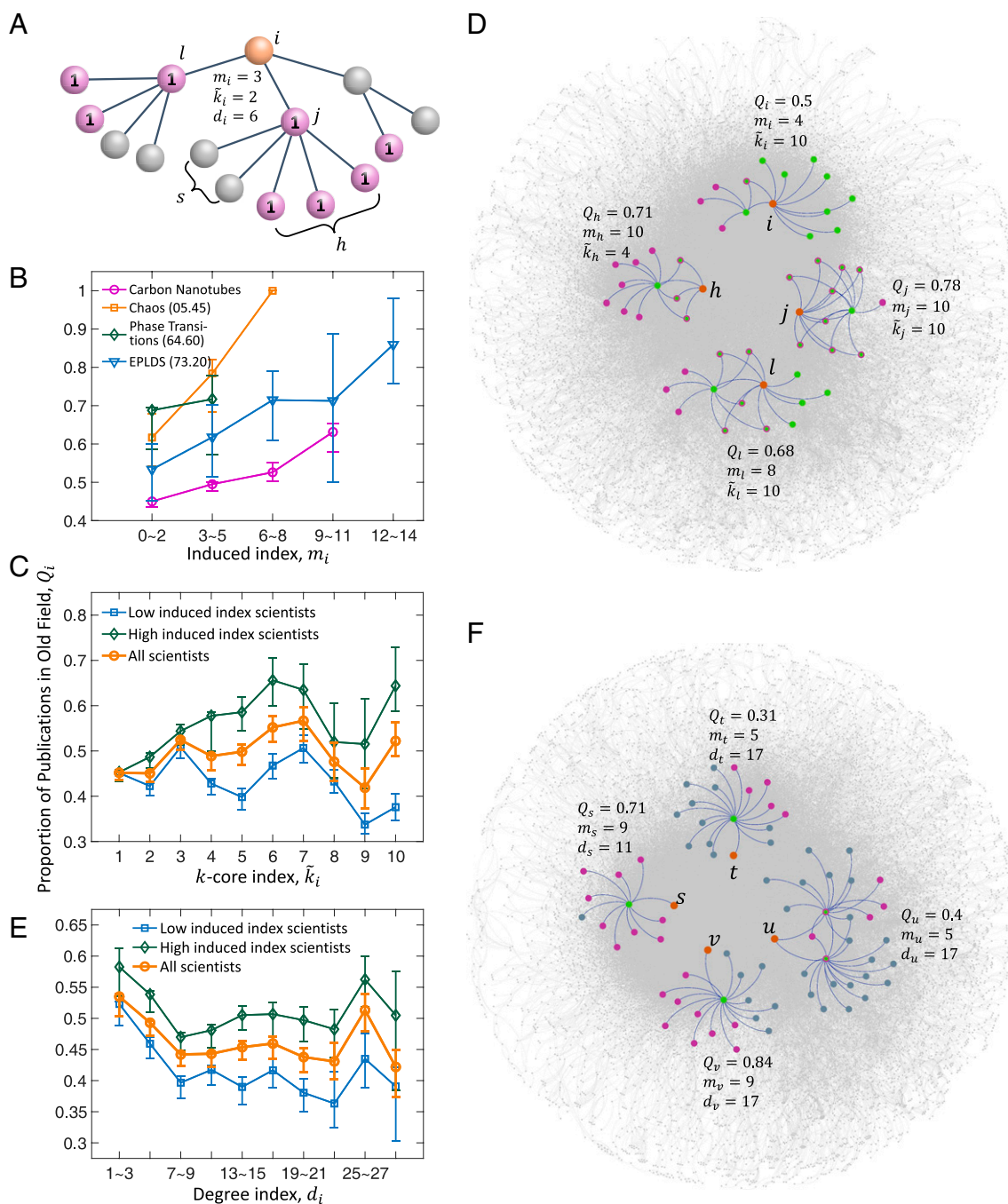


Fig. 1. Indirect influence mechanism in empirical collaboration networks. (A) Schematic representation for the induced index m_i , the k -core index \tilde{k}_i , and the degree index d_i . In this example, “focused” scientists in the established field are denoted as state 1. Node i has an induced index $m_i = 3$ because among all direct neighbors in state 1, node j has the maximum neighbors in state 1 (i.e., three excluding node i). The degree index of node i is $d_i = 6$, which is the degree of node j . The k -core index of node i is $\tilde{k}_i = 2$, which is the number of direct neighbors in state 1 (nodes l and j). (B) Empirical evidence of indirect influence. It shows a clear indirect influence mechanism in four pairs of established and emerging fields in physics that have large numbers of scientists involved. The proportion Q_i of publications in the established fields significantly increases with the scientists’ induced index m_i in all the datasets. To compare with direct influence, the orange lines in C show that the value of Q_i is hardly affected by the direct influence measured through the k -core index, while the scientists with higher indirect influence index (top 50% of m_i values) clearly have a higher Q_i value than that of the lower indirect influence (bottom 50% of m_i values), indicating a strong indirect influence. D highlights four sample scientists (nodes) labeled as h, i, j, l . Each orange node is a node of interest, its connected green nodes are the neighbors of state 1, pink nodes are green nodes’ state-1 neighbors used to calculate induced index m_i . Higher induced index nodes h and j ($m_h = m_j = 10$) publish a proportion $Q_h = 0.71$ and $Q_j = 0.78$ of old field articles, much higher than that of node i with a lower induced index ($m_i = 4$), although i ’s k -core index is higher ($\tilde{k}_i = 10$) than h and the same as j . Comparing node l and i, j again indicates that the influence is stronger through induced index m than that of \tilde{k} . A similar comparison in E and F shows that the proportion Q_i is hardly affected by the degree index but clearly affected by the induced index. C–F show results performed on the collaboration network of carbon nanotubes vs. graphene. Note that in F we also show the state 0 nodes labeled in blue, since the calculation of degree index considers them.

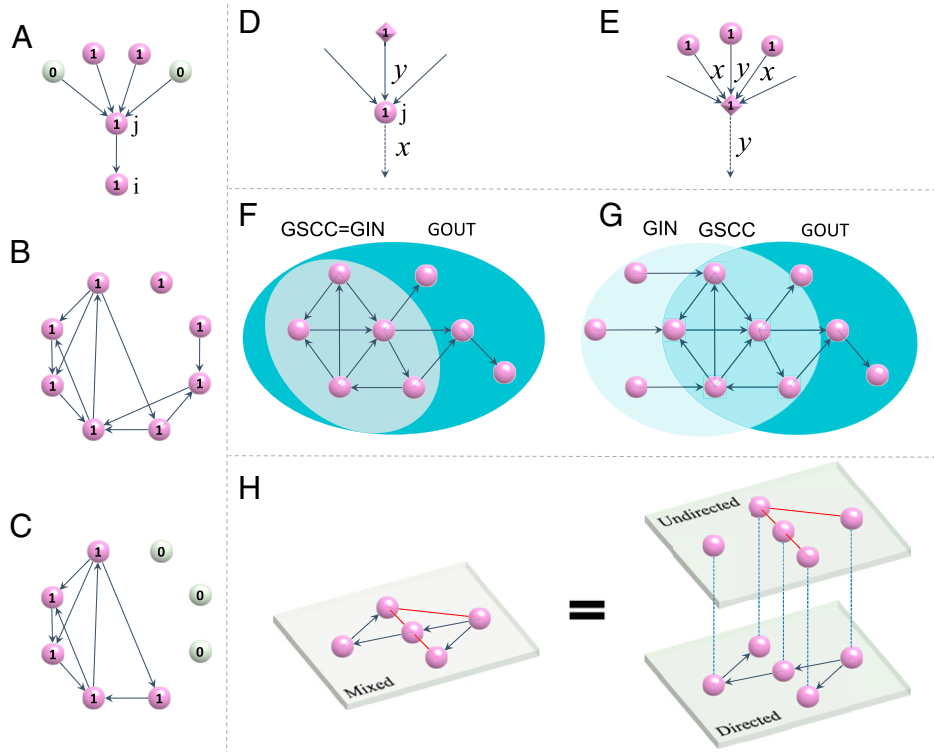


Fig. 2. Induced percolation on directed networks. **A** illustrates the proposed mechanism of induced percolation for the case $m = 2$. In order for a node i to remain in state 1, at least one node (j) at the other end of an incoming link should be in state 1. In its turn, j should also have at least $m (= 2$ in the example) incoming links from neighbors that are in state 1. **B** shows a directed graph of eight nodes all in state 1. **C** shows the GOUT at equilibrium state when the graph on panel **B** is pruned according to the induced percolation rules. **D** and **E** illustrate the variables x and y defined in the main text by Eqs. 3 and 4. **F** and **G** show the relationship between the order parameters GSCC, GIN, and GOUT for induced percolation and typical bond percolation processes, respectively. **H** schematically represents the multilayer representation employed to derive the order parameter P_∞ when there are directed and undirected links in the substrate network.

The observed indirect influence mechanism in empirical collaboration networks is possibly due to the following two factors. First, the fact that a scientist has a high value of induced index means he/she collaborates with a highly active scientist (a state 1 neighbor on its own connecting to a large amount of state 1 neighbors). This active scientist could strongly influence collaborators. Second, researchers who collaborate with highly active scientists have better chances to find new potential collaborators through their connections with respect to researchers who have no highly active neighbors. In other words, scientists with high induced index can interact with researchers of the same field indirectly, through their highly active neighbors.

Induced Percolation Model. We now define a percolation model based only on this indirect influence mechanism characterized by the indirect index m_i . As empirically shown before, the indirect influence increases with m_i . Here we present the most simplified version of this influence mechanism that assumes a deterministic influence outcome, i.e., a node i is influenced to state 1 with probability $h(m_i) = 1$ if its indirect induced index m_i is not smaller than a threshold m (see *SI Appendix, Fig. S20* for a slightly more complicated case):

$$h(m_i) = \begin{cases} 0, & m_i < m, \\ 1, & m_i \geq m. \end{cases} \quad [2]$$

More formally, induced percolation can be defined on directed networks as follows. Let us assume that the state of the nodes is characterized by an integer value, 0 or 1. Initially, we set the state of all nodes in the network to 1. A node i remains in state 1 if at least one of its incoming links comes from a node,

say j , with state 1, and in turn the node j has at least m other incoming links from nodes that are in state 1; see Fig. 2A for an illustration of the case $m = 2$. Otherwise, node i changes to state 0 at the next time step. The influence of the m nodes on the node i defines the indirect interactions among them. Under this mechanism, certain nodes will change their states from 1 to 0 at each time step until no more changes are possible; see Fig. 2B and C for an example. Compared with bond, bootstrap, or k -core percolation, the fundamental difference of induced percolation is that the current state of a node is affected not only by its nearest neighbors but also by a number of its next-nearest neighbors. The mechanism for induced percolation through a network captures the observation that there are behaviors whose influence reaches nodes beyond the first shell.

In network percolation theory, the giant strongly connected component (GSCC), giant in-component (GIN), and giant out-component (GOUT) are three main order parameters. In particular, GSCC refers to the largest strongly connected component whose size is comparable to the entire network. GIN is the group of nodes from which any node in GSCC can be reached, while GOUT is the group of nodes that can be reached from any node in GSCC. For various types of propagation dynamics on networks, the GOUT corresponds to the largest spreading coverage, and it serves as an indicator of network connectivity under a given propagation mechanism. The size of the GOUT in the empirical studies corresponds to the number of scientists who stay in the old field. Therefore, in induced percolation, the main quantity of interest is GOUT (8, 28, 29) and the size of GOUT is the order parameter, i.e., the macroscopic quantity that characterizes phase transitions. In addition, we also examine the size distribution of small outgoing components.

In undirected networks, each link can be viewed as two directed links with opposite directions. Therefore, induced percolation can be studied on fully directed networks, and then the methodology can be extended to either undirected (i.e., fully bidirectional) networks or to networks in which there are both bidirectional and unidirectional links. Note that the GOUT of undirected networks is the same as the GIN and the GSCC. We schematically illustrate the proposed induced percolation mechanism on directed networks in Fig. 2, where we also show the order parameter as compared with the one typically used in bond percolation. Similar diagrams for undirected and mixed networks can be found in *SI Appendix, Figs. S15 and S16*.

The phase transition that characterizes the induced percolation process can be analytically studied on random networks. The class of random directed networks is constructed by independently connecting two arbitrary nodes with a directed link with a fixed probability. The network can be described by the joint degree distribution $P(k_{\text{in}}, k_{\text{out}})$, which is the probability that a randomly selected node has in-degree k_{in} and out-degree k_{out} . For random directed networks, the size of GOUT is derived through the following recursive equations. We first define two recursive variables x and y (see Fig. 2D and E): x represents the probability that when selecting at random a directed link, the node at the origin of the link is active (in state 1), whereas y represents the probability that a random link enables its end node to be in an active state. According to the definitions of x and y , we have

$$x = \sum_{k_{\text{in}}, k_{\text{out}}} \frac{k_{\text{out}} P(k_{\text{in}}, k_{\text{out}})}{\langle k \rangle} \left[1 - (1 - y)^{k_{\text{in}}} \right], \quad [3]$$

where $(1 - y)^{k_{\text{in}}}$ is the probability that none of the incoming k_{in} links can keep node j in state 1 (see Fig. 2A and D), while $1 - (1 - y)^{k_{\text{in}}}$ represents the probability that at least one

of the incoming k_{in} links can keep node j in state 1. The term $\frac{k_{\text{out}} P(k_{\text{in}}, k_{\text{out}})}{\langle k \rangle}$ is the excess incoming degree distribution (28, 29) for the node at the origin of an arbitrary directed link. This is because the likelihood of a node's being the origin of a randomly chosen directed link is proportional to the node's out-degree.

Calculating the probability y is a little more involved. The definition of the induced percolation process implies that even if the starting node of a directed link is active (which happens with probability x), it is not guaranteed that the end node of this directed link remains active (which happens with probability y). However, if the starting node of this directed link is itself active, and at the same time at least m neighbors pointing to the starting node are active, then this directed link can keep its end node active. Conversely, if a directed link can keep the node it points to active (corresponding to y), then the starting node of this directed link must be active (corresponding to x). Therefore, it must hold $x > y$ when $m > 1$ ($x = y$ when $m = 1$ which corresponds to bond percolation). The above analysis yields the expression of y as

$$y = \sum_{k_{\text{in}}, k_{\text{out}}} \frac{k_{\text{out}} P(k_{\text{in}}, k_{\text{out}})}{\langle k \rangle} \sum_{s=m}^{k_{\text{in}}} \binom{k_{\text{in}}}{s} x^s (1-x)^{k_{\text{in}}-s} \left[1 - \left(1 - \frac{y}{x} \right)^s \right], \quad [4]$$

where $\binom{k_{\text{in}}}{s} x^s (1-x)^{k_{\text{in}}-s}$ gives the probability that for a node of incoming degree k_{in} , s out of k_{in} neighbors are active. y/x represents the conditional probability that a directed link keeps its end node active, given the starting node is active. Therefore, $1 - (1 - y/x)^s$ is the probability that at least 1 out of the s active incoming neighbors keeps this node active.

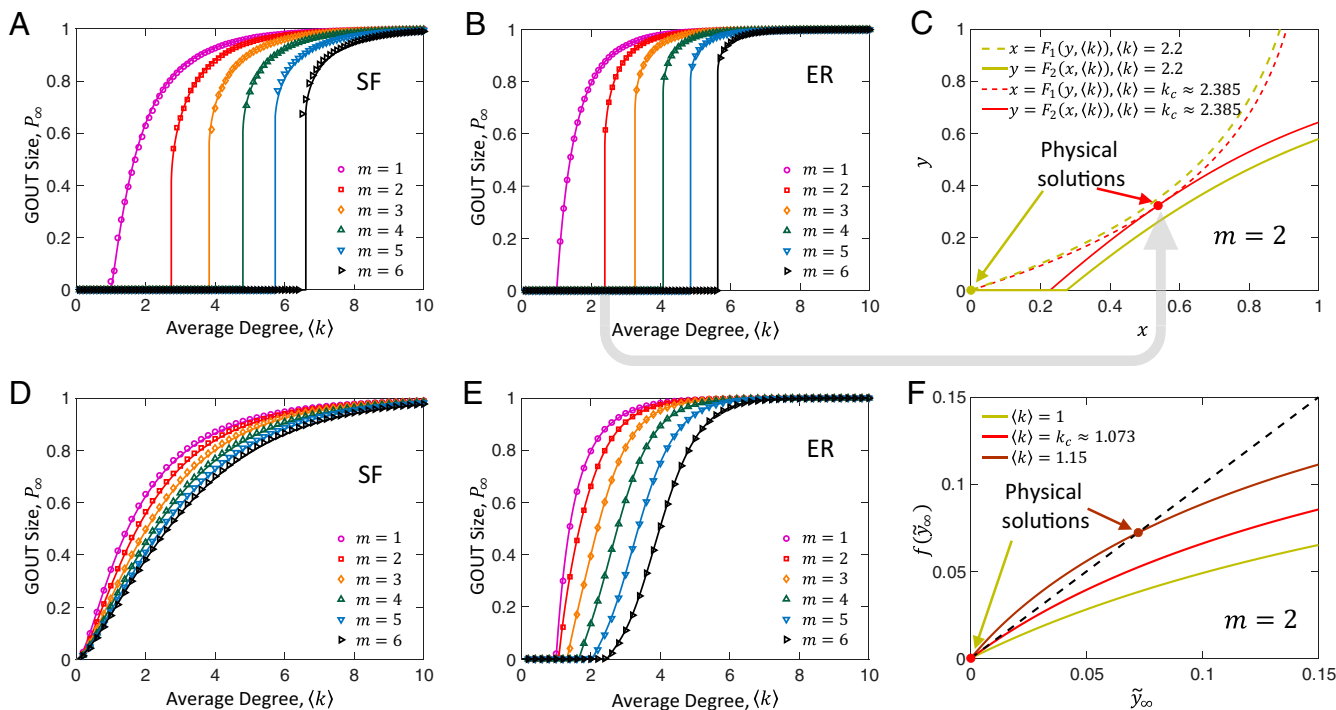


Fig. 3. Order parameter GOUT for induced percolation on directed and undirected random networks. The symbols represent simulation results and the curves are corresponding theoretical results. A and B show GOUT for induced percolation ($m = 2, \dots, 6$) on directed scale-free (SF) and Erdős-Rényi (ER) networks as a function of the average degree $\langle k \rangle$. Results are compared with the behavior of the same order parameter for bond percolation (equivalent to setting $m = 1$). C shows the graphical solution of Eq. 4 for induced percolation ($m = 2$) on directed ER graphs, where k_c is the critical average degree at which a first-order phase transition takes place. D and E show results for undirected networks, whereas the graphical solution shown in F is derived from Eq. 13 (see *Methods*) for induced percolation ($m = 2$) on undirected ER graphs. Directed SF networks are generated by the static model (41, 42) with exponents $\gamma_{\text{in}} = 2.5$ and $\gamma_{\text{out}} = 3.0$ for the incoming and outgoing degree distributions, respectively. Undirected SF networks are generated with the exponent $\gamma = 2.5$.

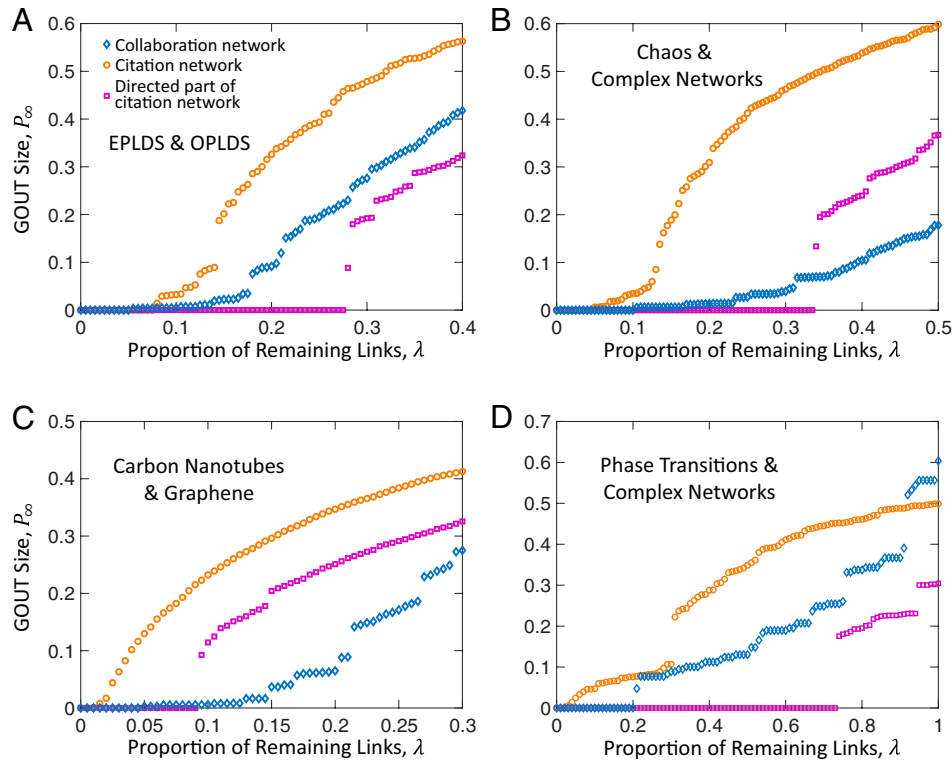


Fig. 4. Order parameter GOUT for induced percolation on empirical networks based on datasets in Table 1. A–D show GOUT as a function of the proportion λ of remaining links. Each point of GOUT is computed as the steady state of induced percolation ($m = 3$) on real-world networks after randomly removing a fraction of $1 - \lambda$ links. The collaboration network is constructed based on published articles within the first 5 y in the four pairs of fields described in Table 1. The directed part of a citation network is obtained by removing all the bidirectional links from the citation network (see *SI Appendix, section 1E*). For the studied four pairs of fields, GOUT in general well agrees with main findings: a continuous, discontinuous, and hybrid phase transition for undirected collaboration networks (blue diamonds), directed part of citation networks (purple squares), and mixed citation networks (orange circles).

Finally, the order parameter P_∞ for the size of GOUT can be calculated based on Eqs. 3 and 4 as follows:

$$P_\infty = \sum_{k_{\text{in}}, k_{\text{out}}}^+ P(k_{\text{in}}, k_{\text{out}}) [1 - (1 - y)^{k_{\text{in}}}] \quad [5]$$

Here P_∞ is equivalent to the probability that a randomly chosen node has at least one incoming node to keep it active. One interesting finding worth highlighting is that the GSCC coincides with the GIN for the induced percolation process on directed networks, which is not the case for classical percolation models (see Fig. 2 F and G). The theoretical analysis of the order parameter P_∞ on undirected networks is illustrated in *Methods*. We also note that the analysis of P_∞ on mixed networks can be done by mapping the structure to a multilayer network; see Fig. 2H and more details in *SI Appendix, section 2*.

Phase Transitions of Induced Percolation. Theoretical analyses allow us to show that the type or order of the phase transition depends on the directionality of the links for the same network connectivity pattern, i.e., the phase transition is anisotropic in nature. On directed networks, when $m > 1$ ($m = 1$ is the case of typical bond percolation), induced percolation shows discontinuous (first-order) phase transitions (see Figs. 3 A–C and 4 A–D for real-world networks). Yet, on undirected networks, the same percolation process always leads to continuous (second-order) phase transitions (see Figs. 3 D–F and 4 A–D for real-world networks). These results are in sharp contrast with previous percolation models on networks (see Table 2), for which it has never been found that the directionality of network links fundamentally alters the type of phase transitions. This means that previously studied types of percolation models might have significantly underestimated the effects of asymmetry in link directions

on the system's macroscopic behavior. An important implication of this observation is that abrupt transitions in complex systems like ecological and social networks might be way more likely to occur than previously anticipated by existing percolation models.

The anisotropy induced by the directionality of the links leads to a rich and complex behavior when the network is composed of a mixture of directed and undirected links. Specifically, a hybrid phase transition emerges with the presence of a certain amount of directed links. Fig. 5 A and B show that by increasing the fraction p of directed links in the network, the order parameter GOUT evolves, as the average degree $\langle k \rangle$ increases, from a continuous transition to a hybrid phase transition where both continuous and discontinuous transition exist, to a first-order transition for larger values of $\langle k \rangle$. In addition, in the region where the hybrid phase transition is observed, several quantities follow a set of scaling relations with critical exponents that are in line with Landau's mean-field theory.

We label the critical hybrid point where the hybrid transition first appears as point $C(k^*, p^*)$ in Fig. 5A. We find a set of scaling relations connecting GOUT to other quantities near C that are predicted by Landau's mean-field theory: Within the hybrid transition, the jump height of GOUT, $\Delta P_\infty(p^* + \Delta p) := \lim_{\langle k \rangle \rightarrow k_c^+} P_\infty(\langle k \rangle, p^* + \Delta p) - \lim_{\langle k \rangle \rightarrow k_c^-} P_\infty(\langle k \rangle, p^* + \Delta p)$, where k_c is the critical point at which the first-order transition occurs, follows a scaling function of Δp with the critical exponent $\eta = 1/2$ (Fig. 5E):

$$\Delta P_\infty(p^* + \Delta p) \sim (\Delta p)^{\frac{1}{2}} \quad [6]$$

The same critical exponent holds for the jump height as a scaling function of $\langle k \rangle - k^*$ as shown in the *SI Appendix, section 5*. When fixing p at p^* and varying $\langle k \rangle$ in the vicinity of k^* , the

Table 2. Comparison of percolation models

Percolation model	Type of phase transition		Clusters distribution near critical point	β	Hybrid phase transition at critical point
	Undirected	Directed			
Induced percolation	Second	First	Nonmonotonic	1 (second) 1/2 (first)	$\theta = 1/3$ $\eta = 1/2$
Bond percolation (5, 8, 9, 28)	Second	Second	Monotonic	1	—
Site percolation (5, 8, 9, 17, 28)	Second	Second	Monotonic	1	—
Bootstrap percolation (18)	Second/first	—	Monotonic	1 (second) 1/2 (first)	$\theta = 1/3$ $\eta = 1/2$
k -core percolation (19)	Second/first	Second/first	—	1 (second) 1/2 (first)	—
Core percolation (26, 27)	Second	Second/first	—	1 (second) 1/2 (first)	—
Explosive percolation (40, 43, 44)	Second	—	—	0.0555	—
Articulation percolation (45)	Second/first	—	—	1 (second) 1/2 (first)	—

Dashes indicate that no related research has been found.

size deviation of GOUT is quantified by the following scaling function of $\langle k \rangle - k^*$ with critical exponent $\theta = 1/3$ (Fig. 5F), reached from both below and above:

$$|P_\infty(\langle k \rangle, p^*) - P_\infty(k^*, p^*)| \sim |\langle k \rangle - k^*|^{\frac{1}{3}}. \quad [7]$$

We note that Baxter et al. also find these two critical exponents in k -core percolation (20).

Another unexpected feature that distinguishes the percolation process formulated here from other percolation is the cluster size distribution near criticality. Typically, for the second-order phase

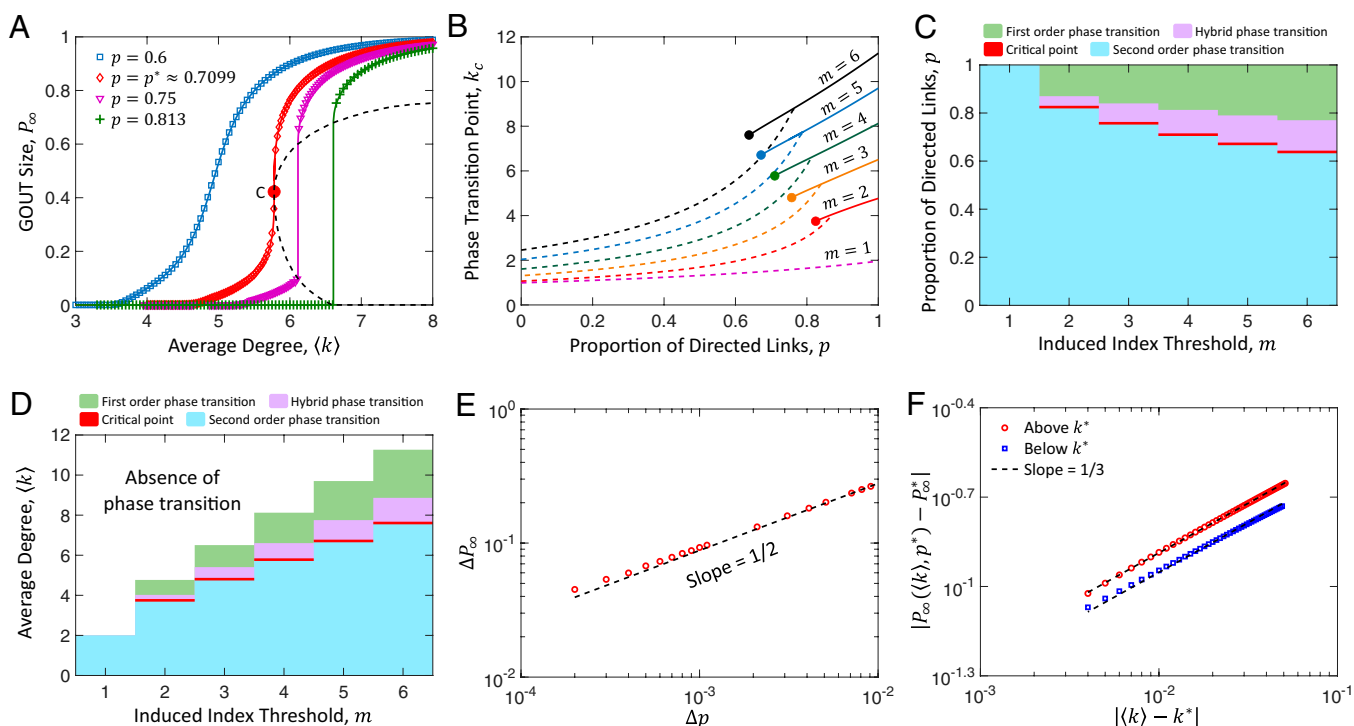


Fig. 5. Phase transitions and critical behaviors of induced percolation on mixed networks. In A, we show theoretical and numerical results for GOUT as a function of the average degree $\langle k \rangle$ when the fraction of directed links is varied. The point C denotes the point at which coexistence of second- and first-order phase transitions occurs for the first time. The curved dotted line represents the value of GOUT before and after the first-order phase transition. The symbols represent simulation results and the curves are corresponding theoretical results. B shows the values of the critical points in the parameter space made up by the average degree and the percentage of directed links; the dotted line describes the critical value at which a second-order phase transition occurs, while the solid line corresponds to the first-order phase transition. Dots correspond to critical points, C. C represents the types of phase transitions that can be observed in the $m - p$ plane. Blue, purple, and green colors bound the area in which second-order, hybrid, and first-order phase transitions exist, respectively. The red boundary lines between the blue and the purple areas correspond to the critical points C. When the parameters are such that they lay on the red line, the behavior of GOUT corresponds to the green line marked with point C in A. D shows the types of phase transitions shown in C but in the $m - \langle k \rangle$ plane. E presents results of the jump size, ΔP_∞ , as a function of $\Delta p = p - p^*$ when the critical point C is approached either from below or from above. F depicts the change of P_∞ near the critical point k^* as a function of $\langle k \rangle - k^*$, when fixing $p = p^*$. The mixed network is generated by assigning a percentage p of directed links to an undirected ER network with an average degree $\langle k \rangle$ and consists of 10^6 nodes.

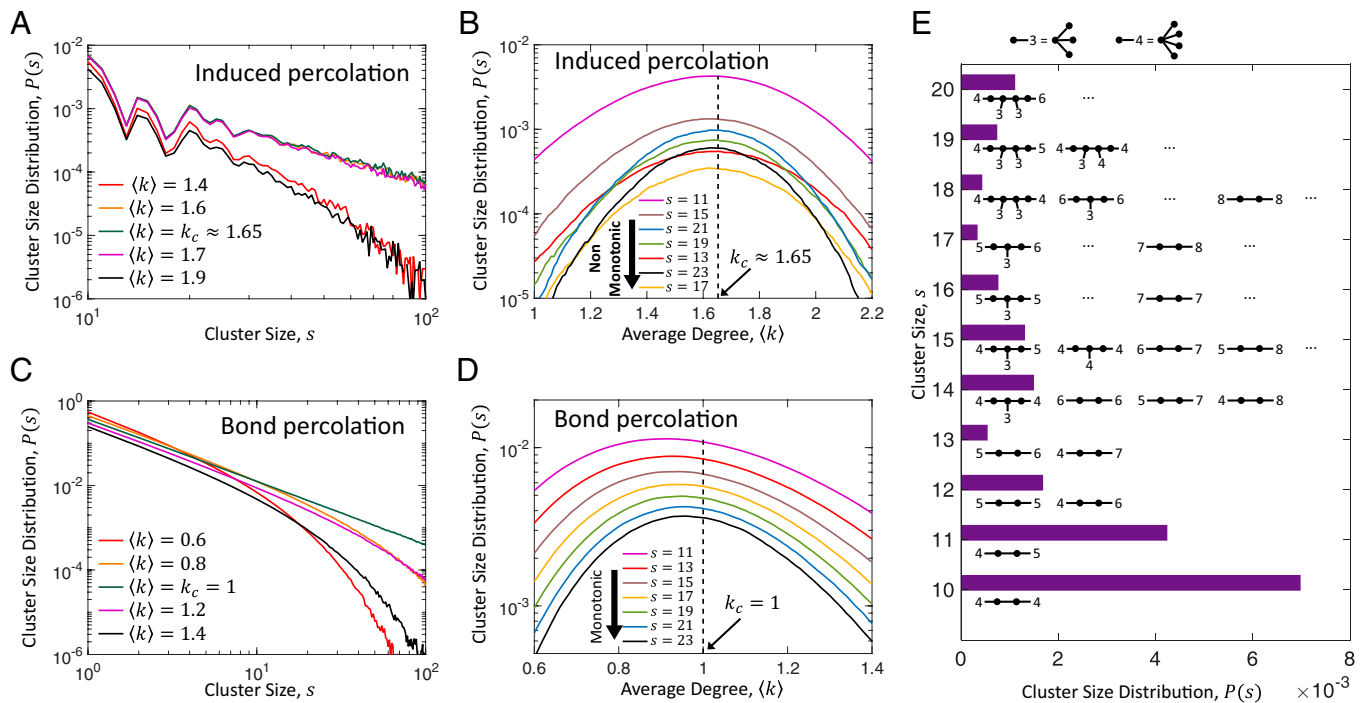


Fig. 6. Size distribution, $P(s)$, of small clusters at the critical point of induced percolation ($m = 4$) on undirected networks. In **A** we show the size distribution, $P(s)$, which exhibits a fluctuating behavior especially for small sizes. **B** plots the same distribution $P(s)$ but as a function of the average degree $\langle k \rangle$, showing an unambiguous nonmonotonic decrease of the size distribution. **C** and **D** depict the monotonous power-law decay of the cluster size distribution in the limit of classical bond percolation. Finally, **E** displays the cluster size distribution at the critical point $k_c \approx 1.65$, also showing the structure of each cluster. Results are averaged over 10^3 independent realizations of undirected Erdős–Rényi networks (of size 10^6 nodes). As it can be clearly seen, the critical behavior of induced percolation is different from that of classical one.

transitions, in the vicinity of the phase transition point, the size distribution of small connected clusters is in general governed by the monotonous function of $P(s) \sim s^{-\tau} e^{-s/s^*}$, where s^* provides a characteristic size of the finite components (4, 10). The closer to the critical point, the larger s^* will be. At the exact phase transition point, s^* approaches infinity and $P(s)$ exhibits a monotonic power-law distribution of $P(s) \sim s^{-\tau}$, signifying a loss of characteristic scale in the distribution. However, for induced percolation on undirected networks, we find that near the critical point $P(s)$ exhibits a novel oscillatory-like behavior, i.e., it is no longer monotonically decreasing with s (see Fig. 6 **A** and **B**).

As it can be seen in the Fig. 6 **A**, **B**, and **E**, the observed oscillatory-like behavior of $P(s)$ is more pronounced for small values of s and does not change the asymptotic power law distribution for large s nor the critical exponent of the phase transition, which is the same as in bond percolation, $\beta = 1$, $\tau = 5/2$ (40). This behavior of $P(s)$ is, however, clearly distinct from the classical monotonic distribution (see Fig. 6 **C** and **D**). We note that we do not have a clear notion of what the exact impact of this pattern on the macroscopic behavior of the system is, which is a question to be further examined in future work.

Conclusion and Discussion

Let us first mention that in addition to our empirical results on collaboration networks we believe that the induced percolation mechanism could play a relevant role in other examples of behavioral influence or contagion, such as in the behavioral spreading of drug abuse, alcoholism, obesity, divorce, happiness, and loneliness, among others. These examples are usually listed to show the “three degrees of influence” mechanism. That is, one individual’s influence can significantly spread out to their friends’ friends’

friends. However, the specific spreading mechanisms behind this phenomenon remain unknown and with no theoretical, first-principled grounds. Although our empirical work reveals only one mechanism of influence within two degrees, we believe that it can be regarded as the first step to provide a specific spreading mechanism for the “three degrees of influence” and potentially opens new paths in the field of percolation on networked systems.

Based on our empirical discovery that indirect influence can dominate over direct influence we have proposed an induced percolation model to characterize the dynamics and outcomes of this indirect spreading mechanism. We found that such indirect interactions lead to a plethora of percolation transitions in complex networks that are rooted in the degree of anisotropy of the connectivity pattern. Specifically, we have shown that the amount of directed links in a network determines the order of the phase transition, which spans from a second order in networks without directed links to a first order when all links are directed. In between, a rich behavior associated with hybrid phase transitions emerges with the coexistence of second- and first-order phase transitions. In addition, the indirect effect makes the size distribution of small clusters near the phase transition point exhibit a nonmonotonic pattern, which has not been previously seen in other percolation models.

Our theoretical framework provides the tools to investigate the implications of having different indirect influence mechanisms in a spreading phenomenon and understand their associated dynamical process and macroscopic spreading outcomes. For instance, we have found that indirect influence can dominate over direct influence in social systems like what we found in scientific collaboration networks—if similar mechanisms in other social behaviors like drug abuse, alcoholism, etc. also hold, this

implies very different mitigation policies from that based on direct influence mechanisms.

Methods

Induced Percolation on Undirected Networks. We elaborate on the definition and the theoretical derivation of induced percolation on undirected networks. All nodes in an undirected network are initially set to state 1. A node l remains in state 1 if at least one of its undirected links has a node j in state 1, and this node j has at least m neighbors (excluding the node l) with state 1 (as illustrated in *SI Appendix, Fig. S16A* for the case of $m = 2$); otherwise, node l changes to state 0 at the next time step. To theoretically analyze the percolating probability that any node belongs to a GCC (giant connected component, equivalent to GOUT), P_∞ , we start by defining six conditional probabilities as intermediate variables, whose notations are shown collectively in *SI Appendix, Fig. S17*. Without loss of generality, we denote a randomly chosen undirected link as $\{j, l\}$ and deduce the probability that node l belongs to a GCC.

According to the definition of induced percolation for undirected networks, the condition for node l to remain active is that there is at least one active neighbor j , and the number \tilde{u} of active neighbors (except node l) of node j satisfies $\tilde{u} \geq m$. We refer to a node in state 1 as an active node and in state 0 as an inactive node. Unlike active neighbors in directed networks, the number \tilde{u} of active neighbors in undirected networks is closely related to the degree k of node j . Specifically, if $k > m$ and node j is active, then node j can keep all its neighbors active. Conversely, if $k \leq m$, then node j cannot keep any of its neighbors active. Hereafter, we employ the degree k instead of the number of active neighbors \tilde{u} to derive percolation probability.

The conditional probability \tilde{v} is the probability that node j can keep node l active, given node l can keep j active. As per the definition of induced percolation, the event of j keeping l active implies that the degree of node j satisfies $k > m$. Node j simultaneously keeps all of its neighbors active. The above analysis yields the following recursive equation:

$$\tilde{v} = \sum_{k=m+1}^{\infty} \frac{kP(k)}{\langle k \rangle}, \quad [8]$$

where $\frac{kP(k)}{\langle k \rangle}$ represents the excess degree distribution of the end node of a randomly chosen link.

On the other hand, the conditional probability \tilde{v}_∞ is defined as the probability that node j can keep node l active, and node l is connected to the GCC via node j , given that node l can keep j active. Again, as per the definition of induced percolation, the degree of node j satisfies $k > m$. Analogously, node j can keep all its neighbors active. In addition, the event that node l connects to GCC through node j is equivalent to the event that node j connects to GCC through at least one of the $k-1$ neighbors other than l . The corresponding probability is $1 - (1 - \tilde{t}_\infty - \tilde{v}_\infty)^{k-1}$ (as shown in *SI Appendix, Fig. S17C*), where the probability $1 - \tilde{t}_\infty - \tilde{v}_\infty$ accounts for the likelihood that one of the $k-1$ neighbors does not belong to the GCC given that node j can keep it active. Therefore, the self-consistent equation for the conditional probability \tilde{v}_∞ can be written as

$$\tilde{v}_\infty = \sum_{k=m+1}^{\infty} \frac{kP(k)}{\langle k \rangle} [1 - (1 - \tilde{t}_\infty - \tilde{v}_\infty)^{k-1}]. \quad [9]$$

In the previous definition, we made use of the conditional probability \tilde{t}_∞ , which is the probability that node j cannot keep node l active while node l connects to GCC through node j , under the condition that node l maintains node j in state 1. Thus, it follows that the degree of node j satisfies $k \leq m$ and that node j cannot keep any of its neighbors active. Moreover, the event in which node l connects to the GCC through node j is equivalent to the event in which node j reaches the GCC through one of the $k-1$ neighbors other than l . The corresponding probability reads $1 - (1 - \tilde{a}_\infty - \tilde{y}_\infty)^{k-1}$ (as shown in *SI Appendix, Fig. S17D*), where the probabilities \tilde{a}_∞ , \tilde{y}_∞ stand for cases in which node j cannot keep any neighbors in state 1 (see below). Therefore, the conditional probability \tilde{t}_∞ can be calculated using

$$\tilde{t}_\infty = \sum_{k=1}^m \frac{kP(k)}{\langle k \rangle} [1 - (1 - \tilde{a}_\infty - \tilde{y}_\infty)^{k-1}]. \quad [10]$$

Once the above probabilities have been defined, we can proceed with the derivation of the remaining three conditional probabilities, namely, \tilde{y} , \tilde{a}_∞ , and \tilde{y}_∞ , which are analogous to \tilde{v} , \tilde{v}_∞ , and \tilde{t}_∞ , but under the condition that node l cannot keep node j active. The derivation of the probability \tilde{y} is similar to \tilde{v} , except that node j relies on at least one of the $k-1$ neighbors (except l) to remain active. This probability can be expressed as

$$\tilde{y} = \sum_{k=m+1}^{\infty} \frac{kP(k)}{\langle k \rangle} [1 - (1 - \tilde{v})^{k-1}]. \quad [11]$$

The derivation of the conditional probability \tilde{a}_∞ is similar to that of \tilde{t}_∞ , except that one additional condition is required: of the $k-1$ neighbors different from l , at least one can keep j active and connected to the GCC. Assuming that there are exactly s ($1 \leq s \leq k-1$) neighbors that can keep node j active, the probability is $\binom{k-1}{s} \tilde{y}^s (1 - \tilde{y})^{k-1-s}$. The probability that node j is connected to the GCC through one of the s neighbors is \tilde{v}_∞^s . For the remaining $k-1-s$ neighbors that cannot keep node j active, the probability of j connecting to the GCC through one of them is $\frac{\tilde{a}_\infty}{1 - \tilde{y}}$. Therefore, the probability that node j is not connected to the GCC through any neighbor is $(1 - \frac{\tilde{v}_\infty}{1 - \tilde{y}})^s (1 - \frac{\tilde{a}_\infty}{1 - \tilde{y}})^{k-1-s}$, as shown in *SI Appendix, Fig. S17F*. Therefore, the self-consistent equation to derive the conditional probability \tilde{a}_∞ is

$$\begin{aligned} \tilde{a}_\infty &= \sum_{k=1}^m \frac{kP(k)}{\langle k \rangle} \sum_{s=1}^{k-1} \binom{k-1}{s} \tilde{y}^s (1 - \tilde{y})^{k-1-s} \\ &\quad \times \left[1 - (1 - \frac{\tilde{v}_\infty}{1 - \tilde{y}})^s (1 - \frac{\tilde{a}_\infty}{1 - \tilde{y}})^{k-1-s} \right] \\ &= \sum_{k=1}^m \frac{kP(k)}{\langle k \rangle} [1 - (1 - \tilde{y})^{k-1} - (1 - \tilde{y}_\infty - \tilde{a}_\infty)^{k-1} \\ &\quad + (1 - \tilde{y} - \tilde{a}_\infty)^{k-1}]. \end{aligned} \quad [12]$$

Finally, the conditional probability \tilde{y}_∞ can be obtained similarly to \tilde{v}_∞ , with the additional consideration that for $k-1$ neighbors except l at least one can keep j active and that node j connects to the GCC via at least one of the $k-1$ neighbors. Thus, the degree of node j satisfies $k > m$, which also implies that j keeps all its neighbors active. Therefore, the conditional probabilities \tilde{y} , \tilde{y}_∞ , and \tilde{a}_∞ in Eq. 12 are replaced by probabilities \tilde{v} , \tilde{v}_∞ , and \tilde{t}_∞ . This leads to the following expression for the conditional probability \tilde{y}_∞ :

$$\begin{aligned} \tilde{y}_\infty &= \sum_{k=m+1}^{\infty} \frac{kP(k)}{\langle k \rangle} \sum_{s=1}^{k-1} \binom{k-1}{s} \tilde{v}^s (1 - \tilde{v})^{k-1-s} \\ &\quad \left[1 - (1 - \frac{\tilde{v}_\infty}{1 - \tilde{v}})^s (1 - \frac{\tilde{t}_\infty}{1 - \tilde{v}})^{k-1-s} \right] \\ &= \sum_{k=m+1}^{\infty} \frac{kP(k)}{\langle k \rangle} [1 - (1 - \tilde{v})^{k-1} - (1 - \tilde{t}_\infty - \tilde{v}_\infty)^{k-1} \\ &\quad + (1 - \tilde{v} - \tilde{t}_\infty)^{k-1}], \end{aligned} \quad [13]$$

where s represents the number of neighbors that can keep j active. The graphical solution of the self-consistent equation \tilde{y}_∞ is shown in the main text, where $f(\tilde{y}_\infty) = F(\tilde{y}_\infty) - \tilde{y}_\infty$ and $F(\tilde{y}_\infty)$ represents the expression on the right-hand side of Eq. 13. The value of $F(\tilde{y}_\infty)$ is obtained by solving the self-consistent Eqs. 8–12.

The previously defined conditional probabilities allow us to derive the order parameter, P_∞ , for induced percolation on undirected networks. For an arbitrarily chosen node l to belong to the GCC, we have that 1) at least one of its neighbors should keep it active and 2) node l is attached to the GCC through at least one of its neighbors. If the degree of node l satisfies $k \leq m$, then the probability that node l belongs to the GCC is $1 - (1 - \tilde{y})^k - (1 - \tilde{y}_\infty - \tilde{a}_\infty)^k + (1 - \tilde{y} - \tilde{a}_\infty)^k$, whose derivation is similar to Eq. 12 in \tilde{a}_∞ . If the degree of node l satisfies $k > m$, then the probability that node l belongs to the GCC is $1 - (1 - \tilde{v})^k - (1 - \tilde{t}_\infty - \tilde{v}_\infty)^k + (1 - \tilde{v} - \tilde{t}_\infty)^k$ and the derivation is similar to \tilde{y}_∞ in Eq. 13. Therefore, the order parameter P_∞ can be computed, for undirected networks, as

$$\begin{aligned} P_\infty &= \sum_{k=0}^m P(k) [1 - (1 - \tilde{y})^k - (1 - \tilde{y}_\infty - \tilde{a}_\infty)^k + (1 - \tilde{y} - \tilde{a}_\infty)^k] \\ &\quad + \sum_{k=m+1}^{\infty} P(k) [1 - (1 - \tilde{v})^k - (1 - \tilde{t}_\infty - \tilde{v}_\infty)^k + (1 - \tilde{v} - \tilde{t}_\infty)^k]. \end{aligned} \quad [14]$$

Data Availability. The data from this study are available at GitHub, <https://github.com/Jia-Rong-Xie>. All other data are included in the main text and/or the *SI Appendix*.

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Supplementary Information for

Indirect influence in social networks as an induced percolation phenomenon

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1. Induced percolation on empirical networks

We present more details of the empirical study here. Considering the spreading dynamics related to human behavior, and at the same time, the availability of high-quality empirical datasets with well categorized research fields, we focus on exploring behavioral influence through induced percolation on scientific collaboration networks. Specifically, when a new research field emerges, scientists either stay in their established field or shift to the emerging field. We therefore want to look at data and empirically inspect scientists' behavior and check whether there are signals that indicate that an induced percolation mechanism might be at work.

To investigate the exact mechanism of scientists' behavior, we choose four pairs of research fields in physics that involve large numbers of scientists: Chaos vs. Complex Networks, Phase Transitions vs. Complex Networks, Electrical Properties of Low-dimensional Structures vs. Optical Properties of Low-dimensional Structures (hereinafter referred to as EPLDS vs. OPLDS), and Carbon Nanotubes vs. Graphene. For each pair of fields, the latter field is the emerging field (new field) that attracts scientists from the former field (old field), which was well established. For the first three pairs of fields, we use data of published articles from the American Physical Society (APS), ranging from 1999-2006 with article field marked by the PACS number. For the fourth pair of fields, a dataset from the Web of Science (1) is employed.

A. Raw data for the empirical study. We analyze the datasets of published articles by American Physical Society (APS) and Web of Science, considered as representative data sources for the studied fields. For the first three pairs of fields, we analyze articles published in APS, containing the publication date, the PACS number and a list of authors for each article. The field to which each article belongs can be identified by PACS numbers. We remove articles consisting of PACS numbers of both the old and new fields to avoid ambiguity. The number of these excluded papers is generally negligible. The excluded papers in the field of Phase Transitions vs. Complex Networks account for 2.7% of the total number of papers (4.2% and 2.2% for the pairs of Chaos vs. Complex Networks and EPLDS vs. OPLDS). In the study of Carbon Nanotubes vs. Graphene, we take the sorted data (1) of articles from Web of Science. The data contains the same information as the APS dataset, and the size is much larger than that of APS.

B. Collaboration network construction. Here we take Chaos vs. Complex Networks as an example, while related descriptions for the rest of pairs of fields are in Table 1 in the main text and Fig. S1. Based on articles in Chaos or Complex Networks, covering in total 5 years (1999-2003) around the emergence of the new field (see Fig. S1), we construct a collaboration network. The nodes are the scientists who have published at least two articles within the five years period, and a link is constructed between any pair of scientists who have at least one joint publication (five articles and two joint publications for nodes and links for Carbon Nanotubes vs. Graphene, extended discussions for parameter robustness in Fig. S7-S13).

On the constructed collaboration network, covering 3 years (2001-2003) around the emergence of the Complex Networks field (see Fig. S1), those scientists who have published at least two (five for Carbon Nanotubes vs. Graphene) articles in Chaos (old field) yet have not published any articles in Complex Networks (new field) are defined as focused scientists in Chaos.

C. Detect the indirect influence mechanism. Specifically, those focused scientists are regarded as the influencers in the collaboration network and labeled as state 1. For any other nodes (influenced) in the network, we calculate the number of direct and indirect 'influencers' for each node. We then observe whether the behaviors of those influenced scientists follow an induced-percolation-like mechanism. For each influenced scientist i , we define two measures or indicators. The first indicator is Q_i , which quantifies the proportion of Chaos papers in the subsequent 3 years (2004-2006). The second indicator is the induced index m_i , corresponding to induced percolation, which quantifies the number of indirect influencers of scientist i . To calculate the induced index, we first identify its state 1 direct neighbors (direct influencers), denoted as the set ∂_i . On each of such neighbors, we count the number of its own state 1 neighbors, and the maximum count is defined as the number of indirect influencers (see Fig. 1A in the main text). The

mathematical expression for the induced index reads:

$$m_i = \max_{j \in \partial_i} |\partial_j \setminus i| \quad [S1]$$

where the set $\partial_j \setminus i$ contains the state 1 neighbors (excluding node i) of a direct neighbor j , and $|\partial_j \setminus i|$ is the set cardinality. To compare with direct influence, we denote \tilde{k}_i as the number of direct influencers of node i , which is the number of its nearest neighbors in state 1. On each of the direct influencers of node i , we further count their own degree and define the maximum degree as degree index d_i .

In the spreading of human behavior, k -core percolation and linear threshold percolation are widely studied models (2–4). That is, the more a person is surrounded by individuals in a certain state (opinions, behaviors, habits), the more likely the person will maintain the same state. Taking Chaos vs. Complex Networks as an example, if this type of percolation exists in the above-analyzed collaboration networks, it would mean that a scientist tends to stay in Chaos if his/her direct collaborators are mostly in Chaos. The orange line in the left column of Fig. S4 and the comparison of lines with different colors in the right column show that Q_i increases with the induced index m_i , indicating that Q_i has a strong correlation with the induced index m_i . Conversely, the orange line in the right column of Fig. S4 and the comparison of the lines with different colors in the left column show that the correlation with k -index is weak, which appears counter-intuitive. Figs. S7-S8,S11 show consistent results when varying parameters in empirical settings. By comparing nodes with the same k -core index, we find that the larger the induced index m_i , the stauncher it is for authors to stay in the Chaos field. On the contrary, it is found that for authors with the same induced index, the value of k -core index has no significant indications. This further shows that there is a remarkable phenomenon of induced percolation in the collaboration network. In addition, the degree distributions after induced percolation and k -core percolation behave differently (Fig. S3).

We also introduce the degree index d_i , which is the highest degree of all stage 1 neighbors of node i . Formally,

$$d_i = \max_{j \in \partial_i} k_j, \quad [S2]$$

where k_j is the degree of node j . We then compare the effect of induced index m_j and degree index d_i in Fig. S5 and find similar results as in Fig. S4.

We further introduce an index κ_i to denote the total number of second-nearest neighbors of node i with state 1. We then compare the index κ_i with the induced index m_i in Fig. S6 (and Figs. S10, S13 for parameter robustness analysis). Results show that Q_i is less associated with the κ_i . Altogether, by comparing the induced index m_i with the k -core index, the degree index, and the second-nearest neighbor index, we show that the proportion of old field publications is dominantly determined by the induced index.

Although we mainly focus on induced percolation for a fixed value of m in our theoretical analysis, the empirical analysis showed that the tendency of state change for a node with different m can be different. As a first proposal of indirect percolation, we consider the induced percolation under a single parameter, which is the most simplified form. A straightforward generalization would be to turn the induced probability from a binary value of 0 or 1 into a continuous function $h(m_i) \in [0, 1]$ of m_i . The function $h(m_i)$ can be interpreted as the probability that a scientist having induced index m_i maintains state 1. The higher the value of m_i , the higher the induced probability $h(m_i)$ which is in line with the empirical results on collaboration networks. Thus, the induced percolation in the main text corresponds to the Heaviside function:

$$h(m_i) = \begin{cases} 0, & m_i < m \\ 1, & m_i \geq m \end{cases} \quad [S3]$$

D. Bias analysis for indirect influence mechanism. Resampling (e.g. bootstrap and jackknife) is widely used to estimate the bias (5). Here, we used bootstrap resampling to investigate the effects of sampling bias. Specifically, we resampled 100% of the articles published in 2004-2006 (2014-2016 for Carbon Nanotubes

vs. Graphene) with replacement, and the error bars in Fig. 1B,C,E and Figs. S4-S13 are 95% confidence interval obtained by 10000 generated resamples.

E. Citation network construction. The citation networks are constructed with the same set of scientists (nodes) as the collaboration networks, while a directed link is constructed if any pair of scientists has one (eight for Carbon Nanotubes vs. Graphene) citation relationship in their published articles. The directed part of a citation networks are obtained by removing all the bidirectional links from the citation networks. The details of the citation networks are shown in Table S1.

F. Indirect influence mechanism mediates collaboration relationship. We analyze whether the indirect relations in the first period will result in more direct collaborations in the later (observation) period through their common direct neighbors (bridge nodes). Taking Fig. S14a (the same with Fig. 1A in the main text) as an example for the node of interest i , we calculate the proportion of publications in the old field where its nearest neighbor j coauthors with both node i and its second-nearest neighbors, and then divide it by the total number of old field publications coauthored by node i and its second-nearest neighbors. In addition, we compare the participation ratio of direct neighbors in two scenarios: that is, node i coauthors with a second-nearest neighbor in state 1 (set h) or in state 0 (set s). The proportion is calculated during the observation period (Carbon Nanotubes vs. Graphene is 2014-2016, the rest pairs are 2004-2006, see Fig. S1, which is also the time interval for calculating Q_i).

Figure S14b shows that among the old field publications: node j is more likely to appear in publications coauthored by i - h rather than those coauthored by i - s . In other words, node i and h , via node j , are more likely to coauthor old field papers in the observation period. This suggests that the quantitative correlation between m_i and Q_i does mediate the collaboration relationship.

2. Induced percolation on mixed networks

Induced percolation on mixed networks with a mix of directed and undirected links is defined as follows. All nodes are initially set to state 1. A node l remains in state 1 if at least one of its undirected or directed links has a node j in state 1, and this node j has at least m neighbors (including in-coming neighbors and undirected neighbors while excluding node l) with state 1 (as illustrated in Fig. S15a for the case of $m = 2$); otherwise node l changes to state 0 at the next time step. The formulation of the induced percolation framework on mixed networks is more complicated than that on directed and undirected networks. One of the main challenges is given by the intertwined effect of directed and undirected edges in maintaining neighbors state and connecting neighbors to the GOUT, which significantly increases the possibilities for a node connecting to GOUT. For example, a mixed network needs to consider staying active through directed neighbors and connecting to GOUT through undirected neighbors, or staying active through undirected neighbors and connecting to GOUT through directed outgoing links, which is not the case for directed and undirected networks. Therefore, in order to deal with this intertwined issue, we employ a multilayer network approach to separate the directed and undirected neighbors by layers. Thus, nodes on the same layer maintain the same pattern in relation to them being active, which enables a recursive calculation. Through aggregation of network layers, we account for all the possibilities in the calculation of the order parameter while effectively avoiding the previous challenge of dealing concurrently with directed and undirected links.

To derive the order parameter for induced percolation on mixed networks, we thus represent a mixed network by a multiplex network: one layer includes undirected links and the other layer includes directed links. A mixed random network is generated by assigning a single direction to an undirected link chosen from an undirected random network. The proportion p of assigned directed links and the average degree $\langle k \rangle$ of the underlying undirected network constitute the parameter space for the generation of mixed networks. In this setting, the average degree in the undirected layer $\langle k \rangle_u$ and the average degree in the directed layer $\langle k \rangle_d$ follow $\langle k \rangle_u = \langle k \rangle (1 - p)$ and $\langle k \rangle_d = \frac{\langle k \rangle p}{2}$. By randomly selecting a directed link in the directed layer, the excess degree distribution of the starting node can be written as $\frac{k_o P(k, k_i, k_o)}{\langle k \rangle_d}$, where k_i , k_o represent the

in-degree and out-degree in the directed layer, respectively, and k is the degree in the undirected layer. Similarly, if an undirected link is randomly chosen in the undirected layer, the excess degree distribution of its end node follows $\frac{kP(k, k_i, k_o)}{\langle k \rangle_u}$. Following the same arguments as for the case of undirected networks, we use the undirected degree k of a node l to deduce the percolation probability, instead of using the number of undirected active neighbors.

On mixed networks, we mainly consider GOUT as the order parameter. For an active node l to be in GOUT, at least one active in-coming or undirected neighbor should belong to the GOUT. For a randomly chosen node l to remain in state 1, the definition of induced percolation implies that there is at least one active neighbor j in the directed layer or at least one active neighbor j in the undirected layer, and node j has s active incoming neighbors in the directed layer and \tilde{u} active neighbors in the undirected layer (excluding node l) satisfying $s + \tilde{u} \geq m$. As noted, given that the number \tilde{u} of active neighbors is closely associated with the undirected degree k of node j , we use k instead of \tilde{u} in deriving GOUT.

To obtain the condition for a node j to keep its neighbors active, we consider three cases separately: (i) If $s + k > m$, then j can maintain neighbors either in the directed layer or in the undirected layer active; (ii) If $s + k < m$, then j cannot keep any neighbors active; (iii) if $s + k = m$, then node j cannot keep its undirected neighbors active, but node j can keep its outgoing neighbors in the directed layer active under the additional condition that all undirected neighbors of j are active ($\tilde{u} = k$).

We start with the definition of a list of intermediate conditional probabilities, as described in Table S2. The order parameter P_∞ is eventually obtained based on solutions of the defined probabilities. We present the definition and the solution of intermediate conditional probabilities one at a time.

The first probability y is defined as the probability that node j can keep node l active through a randomly selected directed link (j, l) . As per the definition of induced percolation, node j can keep node l active if $s + k \geq m$ and j is active. In the case of $s + k > m$, node j is kept active by at least one of the s active in-coming neighbors or k undirected neighbors with probability $1 - \left(\frac{a}{x}\right)^s (1 - \tilde{v})^k$. In the case of $s + k = m$, only when all the undirected neighbors are active, with probability \tilde{x}^k , node j can keep node l active. From the above analysis, the equation for solving the probability y reads

$$y = \sum_{k, k_i, k_o} \frac{k_o P(k, k_i, k_o)}{\langle k \rangle_d} \sum_{s=0}^{k_i} \binom{k_i}{s} (1-x)^{k_i-s} x^s \times \left\{ \mathbb{I}(s+k > m) \left[1 - \left(\frac{a}{x}\right)^s (1-\tilde{v})^k \right] + \mathbb{I}(s+k = m) \left[\tilde{x}^k - \tilde{a}^k \left(\frac{a}{x}\right)^s \right] \right\} \quad [\text{S4}]$$

where $\mathbb{I}(x)$ represents the indicator function of the logical statement x : $\mathbb{I}(x) = 1$ if x is true, otherwise $\mathbb{I}(x) = 0$.

For the probability a , the degree of node j satisfies $s + k \leq m$. When $s + k < m$, node j cannot keep node l active. The probability a thus reduces to the probability of node j remaining active under the condition of having s active in-coming neighbors, which is $1 - \left(\frac{a}{x}\right)^s (1 - \tilde{y})^k$. When $s + k = m$, the probability that node j can not keep node l active follows $1 - \left(\frac{a}{x}\right)^s (1 - \tilde{y})^k - \tilde{x}^k + \tilde{a}^k \left(\frac{a}{x}\right)^s$, where $\left(\frac{a}{x}\right)^s (1 - \tilde{y})^k$ is the probability of j being inactive (in state 0), and \tilde{x}^k is the probability of all undirected neighbors being active. The term $\left(\frac{a}{x}\right)^s \tilde{a}^k$ gives the probability that node j is inactive and at the same time all undirected neighbors are active too. According to the above analysis, the probability a can be obtained as

$$a = \sum_{k, k_i, k_o} \frac{k_o P(k, k_i, k_o)}{\langle k \rangle_d} \sum_{s=0}^{k_i} \binom{k_i}{s} (1-x)^{k_i-s} x^s \times \left\{ \mathbb{I}(s+k \leq m) \left[1 - \left(\frac{a}{x}\right)^s (1-\tilde{y})^k \right] - \mathbb{I}(s+k = m) \left[\tilde{x}^k - \tilde{a}^k \left(\frac{a}{x}\right)^s \right] \right\}. \quad [\text{S5}]$$

For the conditional probability \tilde{v} , the node j can keep node l active if $s + k > m$ and j is active, which also indicates that j can keep all undirected neighbors active. Therefore, the equation for solving the

probability \tilde{v} is

$$\tilde{v} = \sum_{k, k_i, k_o} \frac{kP(k, k_i, k_o)}{\langle k \rangle_u} \sum_{s=0}^{k_i} \mathbb{I}(s+k > m) \binom{k_i}{s} (1-x)^{k_i-s} x^s \quad [S6]$$

The derivation of the conditional probability \tilde{y} is similar to \tilde{v} , except that node l cannot keep node j active. The additional requirement in calculating probability \tilde{y} is that node j is kept active by at least one of s active neighbors in the directed layer and $k-1$ neighbors except l in the undirected layer. The corresponding probability follows $1 - \left(\frac{a}{x}\right)^s (1-\tilde{v})^{k-1}$. Therefore, the corresponding equation to solve \tilde{y} is

$$\tilde{y} = \sum_{k, k_i, k_o} \frac{kP(k, k_i, k_o)}{\langle k \rangle_u} \sum_{s=0}^{k_i} \mathbb{I}(s+k > m) \binom{k_i}{s} (1-x)^{k_i-s} x^s \left[1 - \left(\frac{a}{x}\right)^s (1-\tilde{v})^{k-1} \right] \quad [S7]$$

For the conditional probability \tilde{a} , the event that node j is active but cannot keep node l active indicates $s+k \leq m$. Therefore, the solution to the probability \tilde{a} is similar to Eq. (S5):

$$\tilde{a} = \sum_{k, k_i, k_o} \frac{kP(k, k_i, k_o)}{\langle k \rangle_u} \sum_{s=0}^{k_i} \mathbb{I}(s+k \leq m) \binom{k_i}{s} (1-x)^{k_i-s} x^s \left[1 - \left(\frac{a}{x}\right)^s (1-\tilde{y})^{k-1} \right] \quad [S8]$$

The derivation of the probability y_∞ is analogous to the derivation of the probability y , while an additional requirement is that at least one of the s active neighbors in the directed layer and k neighbors in the undirected layer belong to GOUT. Therefore, the equation to solve y_∞ is expressed as

$$y_\infty = \sum_{k, k_i, k_o} \frac{k_o P(k, k_i, k_o)}{\langle k \rangle_d} \sum_{s=0}^{k_i} \binom{k_i}{s} (1-x)^{k_i-s} x^s \times [\mathbb{I}(s+k > m) Y_1(s, k) + \mathbb{I}(s+k = m) Y_2(s, k)] \quad [S9]$$

where $Y_1(s, k)$ denotes the probability that j connects to GOUT under the conditions $s+k > m$ and j being active. In this case, node j can keep all its undirected neighbors active. According to the definition of induced percolation, at least one of $s+k$ neighbors keeps j active, and j connects to GOUT through at least one of the $s+k$ neighbors. Therefore, the probability $Y_1(s, k)$ is calculated as

$$\begin{aligned} Y_1(s, k) &= \sum_{d=0}^s \sum_{u=0}^k \mathbb{I}(d+u > 0) \binom{s}{d} \left(\frac{y}{x}\right)^d \left(\frac{a}{x}\right)^{s-d} \binom{k}{u} \tilde{v}^u (1-\tilde{v})^{k-u} \\ &\times \left[1 - \left(1 - \frac{y_\infty}{y}\right)^d \left(1 - \frac{a_\infty}{a}\right)^{s-d} \left(1 - \frac{\tilde{v}_\infty}{\tilde{v}}\right)^u \left(1 - \frac{\tilde{t}_\infty}{1-\tilde{v}}\right)^{k-u} \right] \\ &= 1 - \left(1 - \frac{x_\infty}{x}\right)^s (1-\tilde{v}_\infty - \tilde{t}_\infty)^k - \left(\frac{a}{x}\right)^s (1-\tilde{v})^k + \left(\frac{a-a_\infty}{x}\right)^s (1-\tilde{v} - \tilde{t}_\infty)^k \end{aligned} \quad [S10]$$

In addition, $Y_2(s, k)$ represents the probability that (i) node j can keep its out-going neighbor l active and (ii) j connects to GOUT, given the condition $s+k = m$. In this case, node j can keep node l active if all undirected neighbors of j are active. Therefore, $Y_2(s, k)$ is calculated as

$$\begin{aligned} Y_2(s, k) &= \sum_{d=0}^s \sum_{u=0}^k \mathbb{I}(d+u > 0) \binom{s}{d} \left(\frac{y}{x}\right)^d \left(\frac{a}{x}\right)^{s-d} \binom{k}{u} \tilde{y}^u \tilde{a}^{k-u} \\ &\times \left[1 - \left(1 - \frac{y_\infty}{y}\right)^d \left(1 - \frac{a_\infty}{a}\right)^{s-d} \left(1 - \frac{\tilde{y}_\infty}{\tilde{y}}\right)^u \left(1 - \frac{\tilde{a}_\infty}{\tilde{a}}\right)^{k-u} \right] \\ &= \tilde{x}^k - \left(1 - \frac{x_\infty}{x}\right)^s (\tilde{x} - \tilde{x}_\infty)^k - \left(\frac{a}{x}\right)^s \tilde{a}^k + \left(\frac{a-a_\infty}{x}\right)^s (\tilde{a} - \tilde{a}_\infty)^k \end{aligned} \quad [S11]$$

The derivation of the probability a_∞ is similar to y_∞ and a . The probability a_∞ is defined for the event in which j is active but j cannot keep l active, indicating that $s + k \leq m$. However, in the case of $s + k = m$ and if all undirected neighbors of node j are active, node j can keep node l active. The corresponding probability, which reads $\mathbb{I}(s + k = m)Y_2(s, k)$, should be subtracted from the probability a_∞ . Therefore, the probability a_∞ can be written as

$$a_\infty = \sum_{k, k_i, k_o} \frac{k_o P(k, k_i, k_o)}{\langle k \rangle_d} \sum_{s=0}^{k_i} \binom{k_i}{s} (1-x)^{k_i-s} x^s \times [\mathbb{I}(s + k \leq m)Y_3(s, k) - \mathbb{I}(s + k = m)Y_2(s, k)]. \quad [\text{S12}]$$

where $Y_3(s, k)$ denotes the probability that node j connects to GOUT through neighbors other than l , given that $s + k \leq m$,

$$\begin{aligned} Y_3(s, k) &= \sum_{d=0}^s \sum_{u=0}^k \mathbb{I}(d + u > 0) \binom{s}{d} \left(\frac{y}{x}\right)^d \left(\frac{a}{x}\right)^{s-d} \binom{k}{u} \tilde{y}^u (1 - \tilde{y})^{k-u} \\ &\times \left[1 - \left(1 - \frac{y_\infty}{y}\right)^d \left(1 - \frac{a_\infty}{a}\right)^{s-d} \left(1 - \frac{\tilde{y}_\infty}{\tilde{y}}\right)^u \left(1 - \frac{\tilde{a}_\infty}{1 - \tilde{y}}\right)^{k-u} \right] \\ &= 1 - \left(1 - \frac{x_\infty}{x}\right)^s (1 - \tilde{x}_\infty)^k - \left(\frac{a}{x}\right)^s (1 - \tilde{y})^k + \left(\frac{a - a_\infty}{x}\right)^s (1 - \tilde{y} - \tilde{a}_\infty)^k. \end{aligned} \quad [\text{S13}]$$

The probability \tilde{t}_∞ is defined for the event that node j cannot keep node l active and j connects to GOUT through neighbors other than l , given the condition that l can keep j active. The event that j cannot keep node l active indicates $s + k \leq m$. Therefore, we have that

$$\begin{aligned} \tilde{t}_\infty &= \sum_{k, k_i, k_o} \frac{k P(k, k_i, k_o)}{\langle k \rangle_u} \sum_{s=0}^{k_i} \mathbb{I}(s + k \leq m) \binom{k_i}{s} (1-x)^{k_i-s} x^s \\ &\times \left[1 - \left(1 - \frac{x_\infty}{x}\right)^s (1 - \tilde{x}_\infty)^{k-1} \right] \end{aligned} \quad [\text{S14}]$$

Probabilities \tilde{v}_∞ , \tilde{y}_∞ and \tilde{a}_∞ are derived analogously to \tilde{v} , \tilde{y} and \tilde{a} , except that additional conditions are required: node j connects to GOUT through at least one of the s active in-coming neighbors and $k - 1$ undirected neighbors (except l). Therefore, the probability \tilde{v}_∞ is obtained from

$$\begin{aligned} \tilde{v}_\infty &= \sum_{k, k_i, k_o} \frac{k P(k, k_i, k_o)}{\langle k \rangle_u} \sum_{s=0}^{k_i} \mathbb{I}(s + k > m) \binom{k_i}{s} (1-x)^{k_i-s} x^s \\ &\times \left[1 - \left(1 - \frac{x_\infty}{x}\right)^s (1 - \tilde{v}_\infty - \tilde{t}_\infty)^{k-1} \right] \end{aligned} \quad [\text{S15}]$$

and

$$\tilde{y}_\infty = \sum_{k, k_i, k_o} \frac{k P(k, k_i, k_o)}{\langle k \rangle_u} \sum_{s=0}^{k_i} \mathbb{I}(s + k > m) \binom{k_i}{s} (1-x)^{k_i-s} x^s Y_1(s, k-1) \quad [\text{S16}]$$

where $Y_1(s, k-1)$ means that (i) j can keep the undirected neighbor l active, and (ii) j connects to GOUT through nodes other than l , given that $s + k > m$. The value of $Y_1(s, k-1)$ is obtained from the equation Eq. (S10). Analogously, the probability \tilde{a}_∞ is expressed as

$$\tilde{a}_\infty = \sum_{k, k_i, k_o} \frac{k P(k, k_i, k_o)}{\langle k \rangle_u} \sum_{s=0}^{k_i} \mathbb{I}(s + k \leq m) \binom{k_i}{s} (1-x)^{k_i-s} x^s Y_3(s, k-1) \quad [\text{S17}]$$

where $Y_3(s, k-1)$ represents the probability that j connects to GOUT through neighbors other than l , given that $s+k \leq m$, whose value is determined by the equation Eq. (S13).

Based on the solutions of the above defined probabilities, the order parameter GOUT on mixed networks can be calculated considering two contributions. When the total number of active neighbors s in the directed layer and the number k of neighbors in the undirected layer satisfies $s+k > m$ and when j is active, node j can keep all the undirected neighbors active. The probability that j belongs to GOUT is $Y_1(s, k)$. However, when $s+k \leq m$, node j cannot keep any of its undirected neighbors active. The probability that node j belongs to GOUT is $Y_3(s, k)$. Finally, the order parameter GOUT is given by

$$P_\infty = \sum_{k, k_i, k_o}^{\infty} P(k, k_i, k_o) \sum_{s=0}^{k_i} \binom{k_i}{s} (1-x)^{k_i-s} x^s \times [\mathbb{I}(s+k > m)Y_1(s, k) + \mathbb{I}(s+k \leq m)Y_3(s, k)] \quad [\text{S18}]$$

where $Y_1(s, k)$ and $Y_3(s, k)$ are established in equations Eqs. (S10) and (S13).

3. Induced percolation on undirected networks

We presented the theoretical analysis of induced percolation on undirected networks in the Methods section of the main text. Here, we supplement the analysis with illustrations on the definition of induced percolation on undirected networks (as shown in Fig. S16). In addition, we illustrate the relation between conditional probabilities (as shown in Fig. S17) defined when deriving the order parameter P_∞ on undirected networks. According to the definition of induced percolation, even on an acyclic random undirected network, there will be a special kind of short-range feedback, termed as reciprocal feedback (see Fig. S2), which complicates the theoretical analysis.

4. Order parameters in directed networks

In directed networks, there are three types of giant connected components: giant strongly connected component (GSCC), giant out-going component (GOUT) and giant in-coming component (GIN), as shown in Fig. 2 in the main text. Analogous to “component” in undirected networks, there is a related concept in directed networks: strongly connected component (SCC). A strongly connected component is a group of nodes within which any pair of nodes are mutually reachable. The giant strongly connected component (GSCC) refers to the largest strongly connected component whose size is comparable with the entire network. Based on GSCC, two related concepts are built: giant out-component (GOUT) and giant in-component (GIN). GOUT is the group of nodes that can be cascaded to from any node in GSCC, while GIN is the group of nodes from which every node in GSCC can be cascaded to. The definition implies that GSCC is a subset of GOUT and GIN. In undirected networks, GSCC, GIN and GOUT are the same set of nodes.

5. Scaling behaviors near the critical points

Although the scaling relations around the critical hybrid point has been so far done for a single fixed network parameter, the scaling relation and the association to Landau’s mean-field theory can be generalized to different network parameters. Specifically, we further present the generalization of the jump of GOUT and the size deviation of GOUT for mixed networks at the critical hybrid point $C(k^*, p^*)$.

The order parameter P_∞ on mixed networks exhibits hybrid phase transitions with the presence of certain amount of directed links. Within the hybrid transition, variables of P_∞ follow a set of scaling relations with critical exponents in line with Landau’s mean-field theory. Specifically, the size of the jump of GOUT, $\Delta P_\infty := \lim_{p \rightarrow p_c^-} P_\infty(k^* + \Delta k, p) - \lim_{p \rightarrow p_c^+} P_\infty(k^* + \Delta k, p)$, where p_c is the critical point at which the first order transition occurs, follows a scaling function of Δk with the critical exponent $\eta = 1/2$ (Fig. S18)

$$\Delta P_\infty(k^* + \Delta k) \sim (\Delta k)^{\frac{1}{2}}. \quad [\text{S19}]$$

The scaling relation between ΔP_∞ and $p - p^*$ is presented in the main text. If $\langle k \rangle$ is fixed at k^* and we vary p in the vicinity of p^* , the size deviation of GOUT can be quantified by the following scaling function of $p - p^*$ with critical exponent $\theta = 1/3$ (Fig. S19), reached from both below and above,

$$|P_\infty(k^*, p) - P_\infty^*(k^*, p^*)| \sim |p - p^*|^{\frac{1}{3}}. \quad [\text{S20}]$$

The scaling behavior of GOUT when fixing p at p^* is presented in the main text.

6. Generation of scale free networks

To verify the theoretical analysis of induced percolation, we present the order parameter GOUT on scale-free networks, generated under a wide range of degree exponents. The undirected scale-free (SF) networks show power-law degree distribution as $P(k) \propto k^{-\gamma}$ with γ as the degree exponent. The SF networks can be generated with the configuration model, which is a process based on the degree sequence for nodes derived directly from the degree distribution. The static model (6, 7) can also be adopted to generate both undirected and directed random graphs, which are asymptotically scale-free at large degrees.

We first consider the construction of undirected SF networks with the static model. Here we generate approximately an undirected SF network instance with a degree exponent γ of N nodes and an average degree $\langle k \rangle$. Initially, a null graph has a given collection of N nodes with labels $i = 1, 2, \dots, N$ with no links. Each node is assigned with a weight as $w(i) \sim i^{-\xi}$ with $\xi \equiv 1/(\gamma - 1)$. Then a size of $M = \langle k \rangle N/2$ links are added into the null graph one by one. For each link, two distinct end-nodes are chosen randomly with probabilities to their respective weights. The degree distribution of the graphs generated by the static model has an analytical form. For the case of SF networks with a mean degree $\langle k \rangle$, we have (6, 7)

$$P(k) = \frac{1}{\xi} \frac{(\langle k \rangle (1 - \xi))^k}{k!} E_{-k+1+\frac{1}{\xi}}(\langle k \rangle (1 - \xi)), \quad [\text{S21}]$$

$$Q(k) = \frac{1 - \xi}{\xi} \frac{(\langle k \rangle (1 - \xi))^{k-1}}{(k-1)!} E_{-k+1+\frac{1}{\xi}}(\langle k \rangle (1 - \xi)). \quad [\text{S22}]$$

The equation $E_\alpha(x) \equiv x^{\alpha-1} \Gamma(1 - \alpha, x)$, with $\Gamma(1 - a, x)$ as an upper incomplete gamma function. For large k , we have $P(k) \propto k^{-\gamma}$. We can derive the summation rule as

$$\sum_{k=0}^{+\infty} P(k) x^k = \frac{1}{\xi} E_{1+\frac{1}{\xi}}(\langle k \rangle (1 - \xi)(1 - x)), \quad [\text{S23}]$$

$$\sum_{k=1}^{+\infty} Q(k) x^{k-1} = \frac{1 - \xi}{\xi} E_{s=0}(\langle k \rangle (1 - \xi)(1 - x)). \quad [\text{S24}]$$

The directed scale-free networks with exponential degree distribution for both in-degrees and out-degrees can also be generated with the static model. For example, we generate here a directed SF network instance with an in-degree exponent γ_{in} and an out-degree exponent γ_{out} of N nodes and an average degree $\langle k \rangle$. We first define two parameters $\xi_{\text{in}} \equiv 1/(\gamma_{\text{in}} - 1)$ and $\xi_{\text{out}} \equiv 1/(\gamma_{\text{out}} - 1)$. Initially, for a null graph with N nodes with labels $i = 1, 2, \dots, N$ without links, each node is assigned with two weights, the in-weight $w_{\text{in}}(i) \sim i^{-\xi_{\text{in}}}$ and the out-weight $w_{\text{out}}(i) \sim i^{-\xi_{\text{out}}}$. To decouple the correspondence between the in-node and out-node weights, a permutation process can be carried out for the in-node or out-node weights or both. Then a number of links $M = \langle k \rangle N$ are added into the null graph. In each link addition step, two distinct nodes i and j are chosen with probabilities proportional to the out-weight and in-weight of nodes respectively, and then an link (i, j) as $i \rightarrow j$ is established. For large k_{in} and k_{out} , the graph instance shows a degree distribution $P(k_{\text{in}}, k_{\text{out}}) \approx k_{\text{in}}^{-\gamma_{\text{in}}} \times k_{\text{out}}^{-\gamma_{\text{out}}}$. The set of summation formulae like those in the context of undirected graphs can also be derived.

7. Induced percolation with heterogeneous induced index threshold

The induced percolation (see Eq. [2] in the main text) corresponds to the Heaviside function, which can be generalized to a slightly complicated form, for example,

$$h(m_i) = \begin{cases} 0, & m_i = 0 \\ r, & m_i = 1 \\ 1, & m_i \geq 2 \end{cases} \quad [\text{S25}]$$

For a high value of r , the network disintegrates in a form of a continuous phase transition, whereas for a low value of r , the network disintegrates in a first order transition (see Fig. [S20](#)).

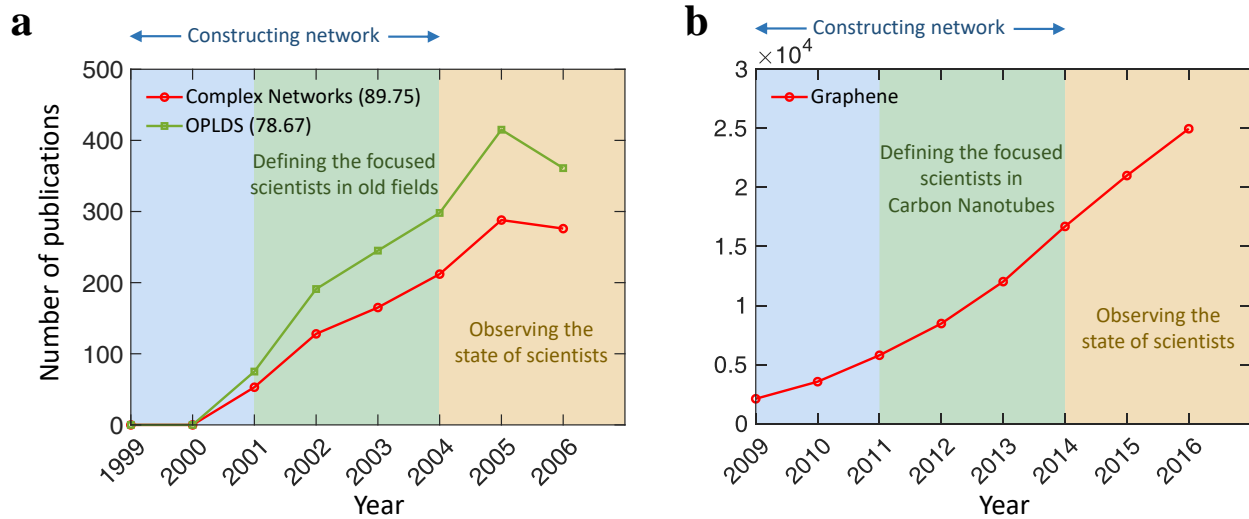


Fig. S1. Illustration of the empirical analysis performed over a period of eight years. Panel (a) shows the period used to construct collaboration networks, from which “focused” scientists and scientists behavioral changes in research focus are extracted. Solid lines show the numbers of publications in Complex Networks and OPLDS, characterizing the emergence of new fields. (b) shows the time windows used for Carbon Nanotubes vs. Graphene. The solid line shows the numbers of publications in the emerging field of Graphene.

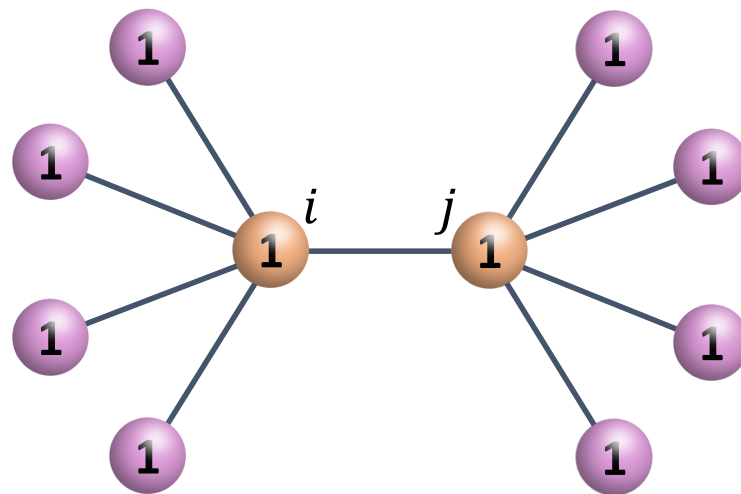


Fig. S2. Schematic representation of reciprocal feedback. For a 4-induced percolation, nodes i and j have a reciprocal feedback effect at inducing each other to maintain their states. If one neighbor of node j is removed, the mutual induction is destroyed, and all state 1 neighbors will change to state 0.

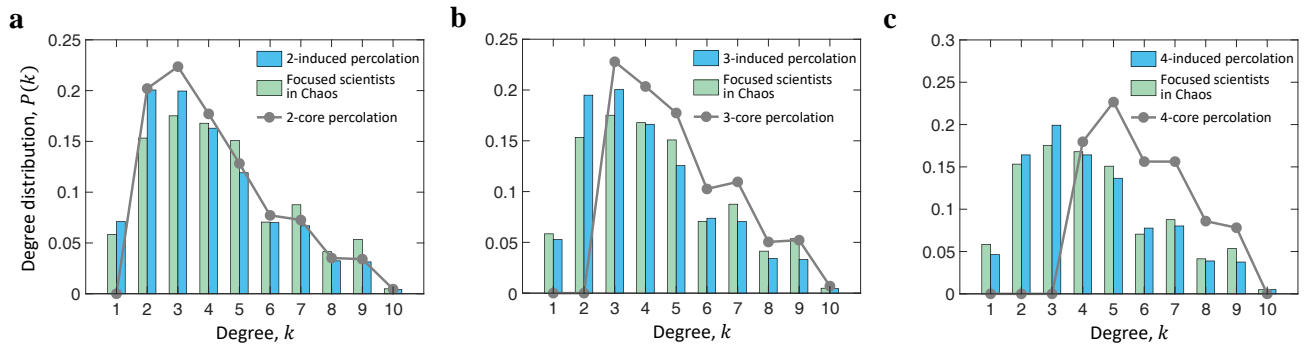


Fig. S3. Empirical degree distribution described by the induced percolation and the k -core percolation. On the constructed empirical collaboration network of Chaos vs. Complex Networks (1999-2003), we perform the induced percolation and the k -core percolation and show the degree distribution in the giant connected component (equivalent to GOUT in directed networks). Panels (a)-(c) show the induced percolation of $m = 2, 3, 4$ and k -core percolation of $k = 2, 3, 4$.

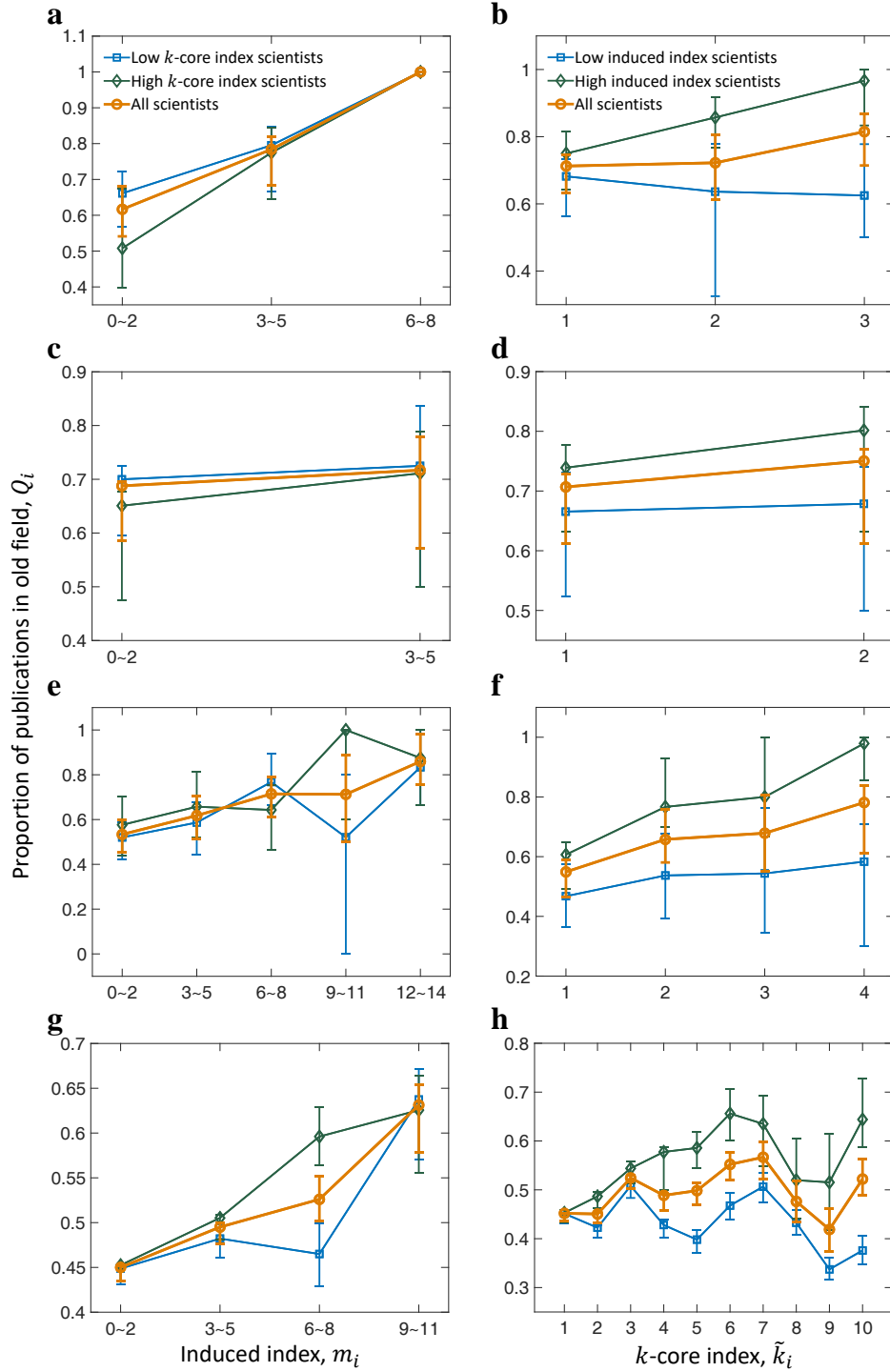


Fig. S4. Comparison between the induced index and the k -core index. Empirical analyses include four pairs of fields: (a-b) Chaos vs. Complex Networks; (c-d) Phase Transitions vs. Complex Networks; (e-f) EPLDS vs. OPLDS; (g-h) Carbon Nanotubes vs. Graphene. Left panels (a,c,e,g) show the proportion Q_i of publications in the old field as a function of the induced index m_i . The proportion Q_i is averaged over authors with induced index (orange line). To compare with the k -core percolation, we separately plot Q_i for two groups of scientists of top and bottom 50% of k -core index values, shown as the green and blue lines. Likewise, the right panels (b,d,f,h) show Q_i as a function of the k -core index and the separated Q_i for two groups of top and bottom 50% of induced index. In the left panels, the trend of Q_i is strongly determined by the induced index, irrespective of the division of high or low k -core index groups. However, in the right panels, the trend of Q_i is hardly affected by the k -core index. Conversely, fixing k -core index, the proportion Q_i of higher induced index is always larger than those of lower induced index.

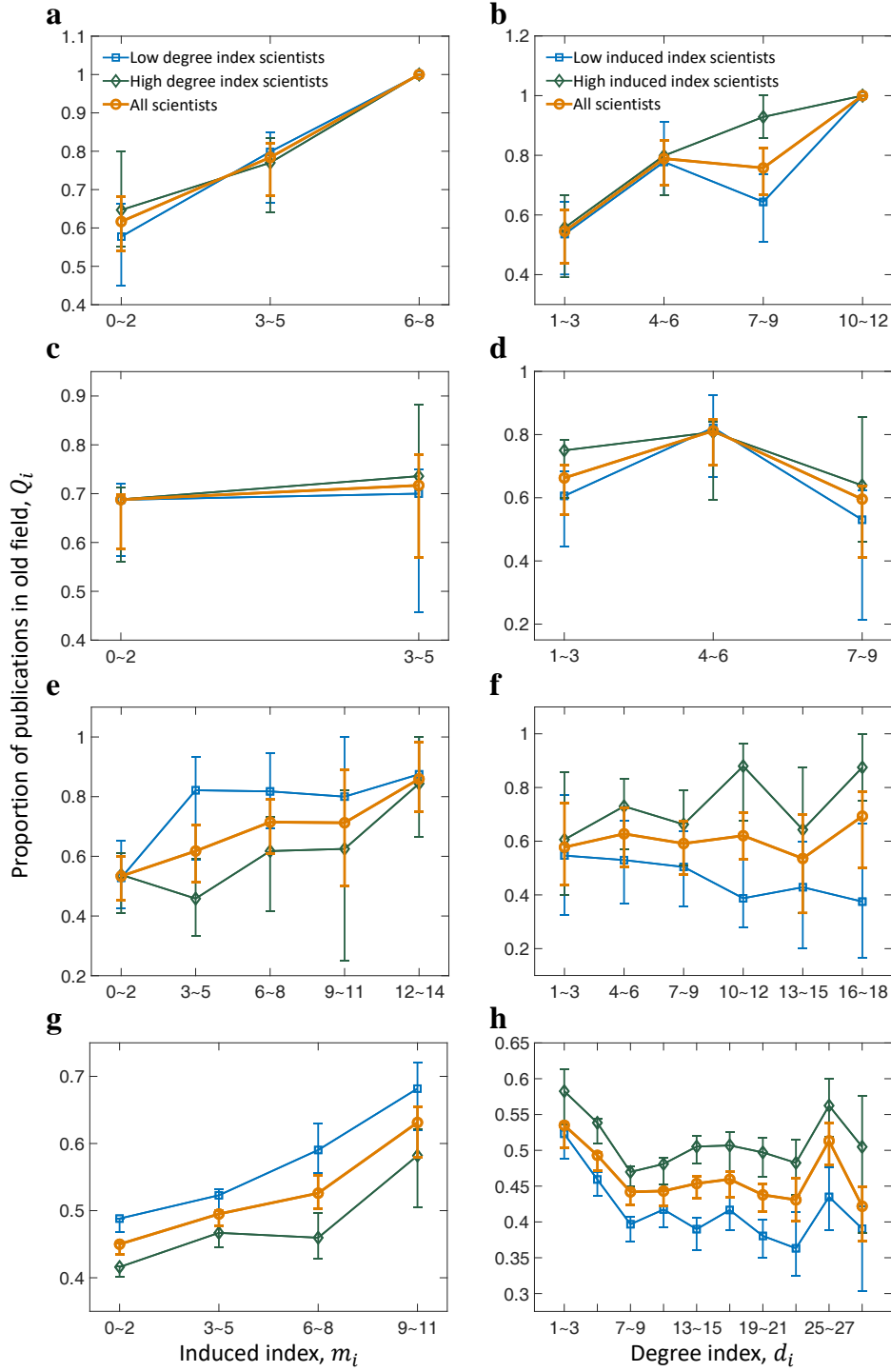


Fig. S5. Comparison between the induced index and the degree index. Left panels (a,c,e,g) show the proportion Q_i of publications in the old field as a function of the induced index m_i . The proportion Q_i is averaged over authors with induced index (orange line). We separately plot Q_i for two groups of scientists, namely, top and bottom 50% of degree index values (green and blue lines). Likewise, the right panels (b,d,f,h) show Q_i as a function of the degree index and the separated Q_i for the two groups of top and bottom 50% of induced index. In the left panels, the trend of Q_i is strongly determined by the induced index, irrespective of the division of high or low degree index. However, in the right panels, the trend of Q_i is hardly affected by the degree index. Conversely, fixing the degree index, the proportion Q_i of higher induced index is almost always larger than those of lower induced index.

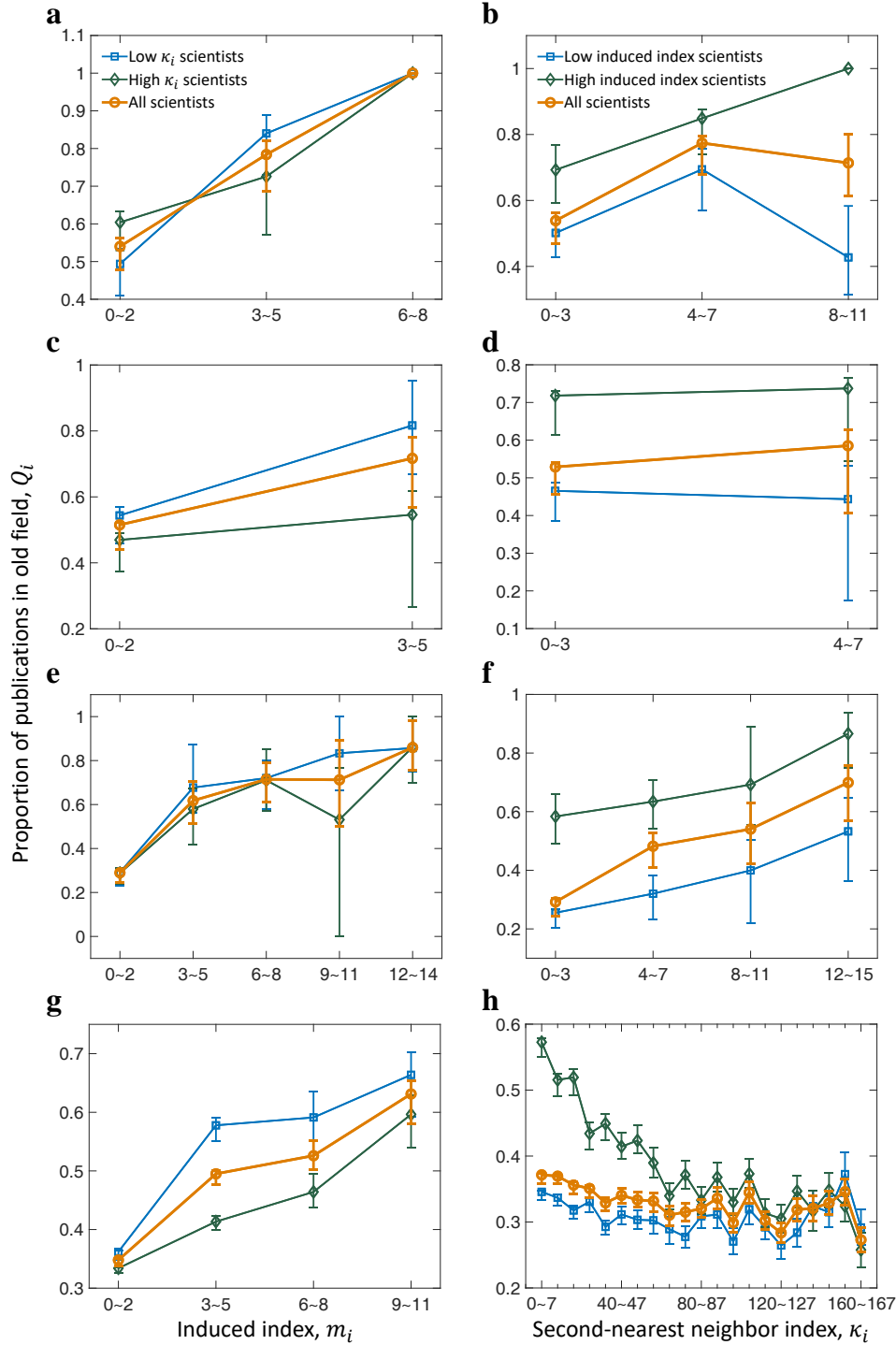


Fig. S6. Comparison between the induced index and the second-nearest neighbor index. Left panels (a,c,e,g) show the proportion Q_i of publications in the old field as a function of the induced index m_i . To compare with the second-nearest neighbor index κ_i , we separately plot Q_i for two groups of scientists that correspond to the top and bottom 50% of second-nearest neighbor index, shown as the green and blue lines. Likewise, the right panels (b,d,f,h) show Q_i as a function of the second-nearest neighbor index κ_i . Similarly, the green and blue lines of Q_i correspond to the scientists at the top and bottom 50% of the induced index. In the left panels, the trend of Q_i is strongly determined by the induced index, irrespective of the division of high or low second-nearest neighbor index groups. However, in the right panels, the trend of Q_i is less relevant with the second-nearest neighbor index. Conversely, fixing the second-nearest neighbor index, the proportion Q_i for scientists with a higher induced index is always larger than the proportion for scientists with a lower induced index.

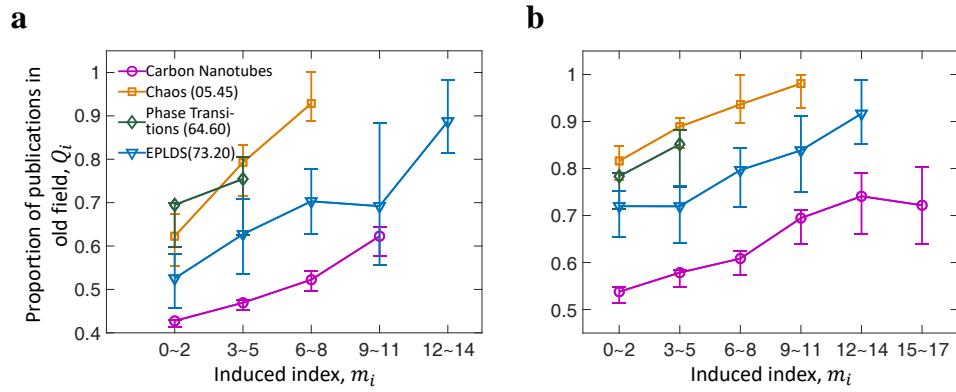


Fig. S7. Parameter robustness in observing the induced effect. Panel (a) shows the result of lengthening the observation period by one year (2004-2007 for the first three pairs of fields, and 2014-2017 for the Carbon Nanotubes vs. Graphene field). Panel (b) shows the result of including more authors in the constructed networks: for the first three pairs, all authors that published at least 1 instead of 2 papers in 1999-2003 are included; for the fourth pair, all authors that published at least 2 instead of 5 papers in 2009-2013 are included.

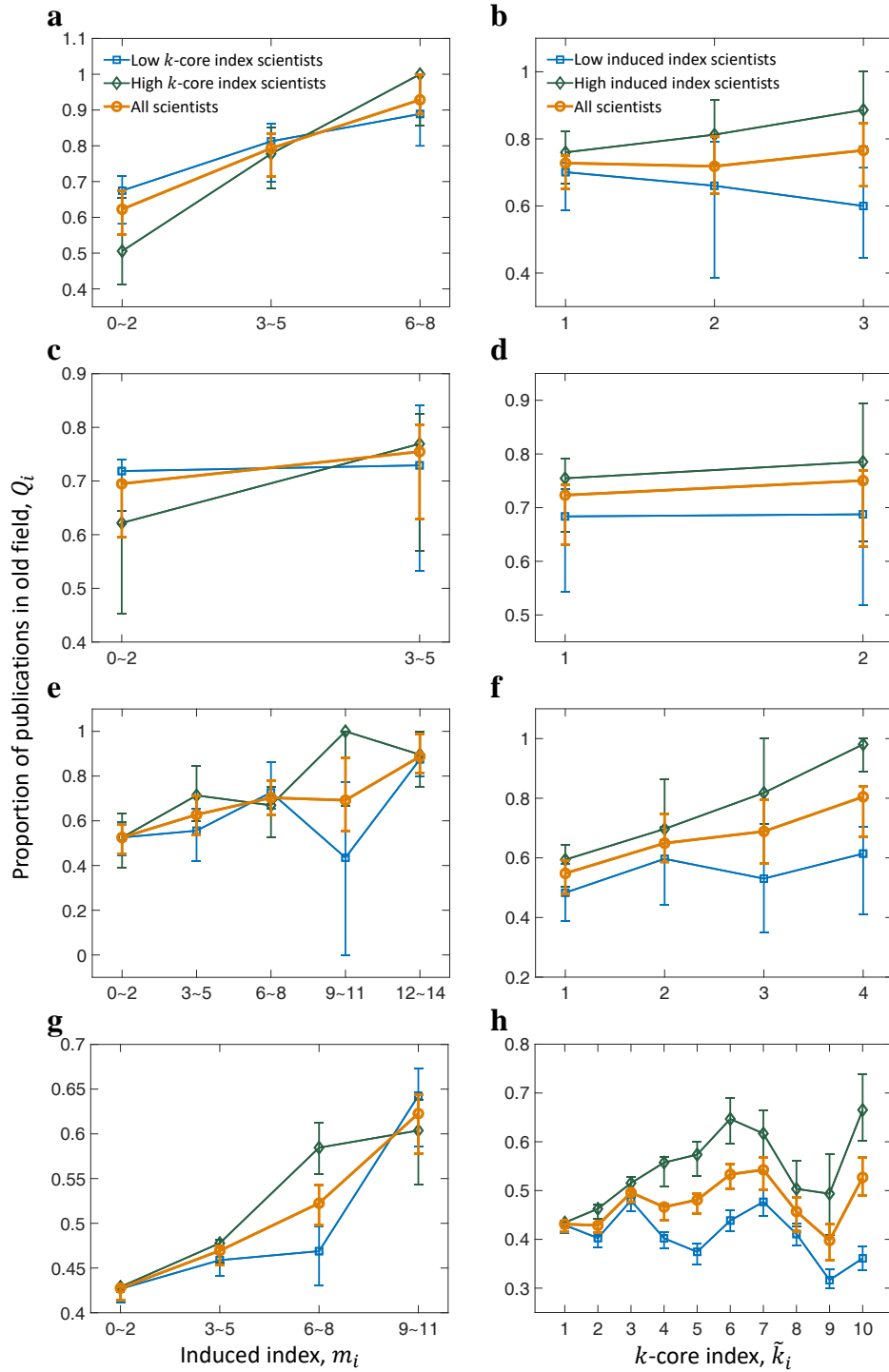


Fig. S8. Parameter robustness in comparing the induced index with the k -core index. All results are obtained by lengthening the state observation period by one year (2004-2007 for the first three pairs of fields, and 2014-2017 for Carbon Nanotubes vs. Graphene). The remaining parameters are kept the same as in Table 1 of the Main text.

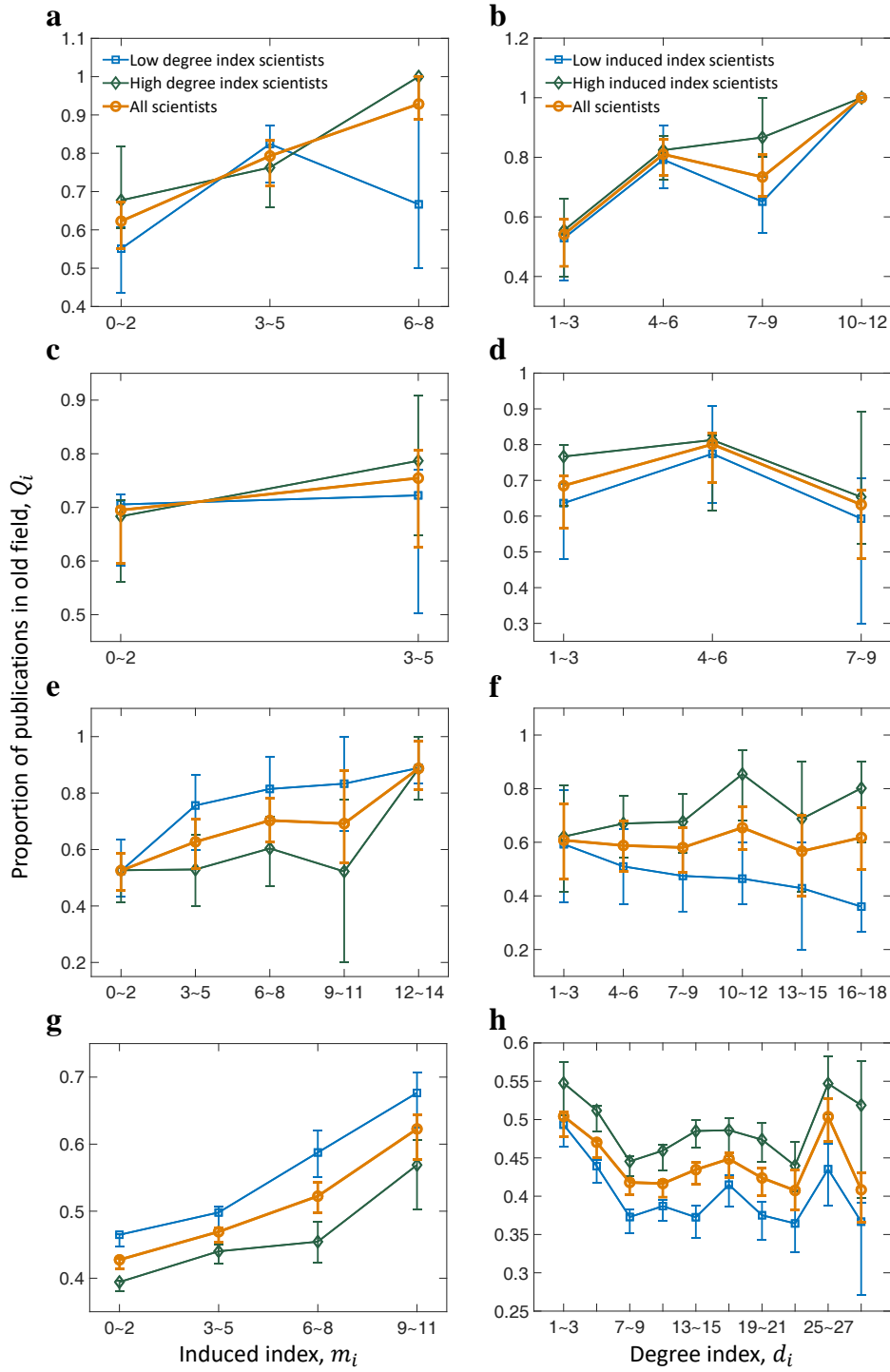


Fig. S9. Parameter robustness in comparing the induced index with the degree index. Parameter settings follow the same as Fig. S8.

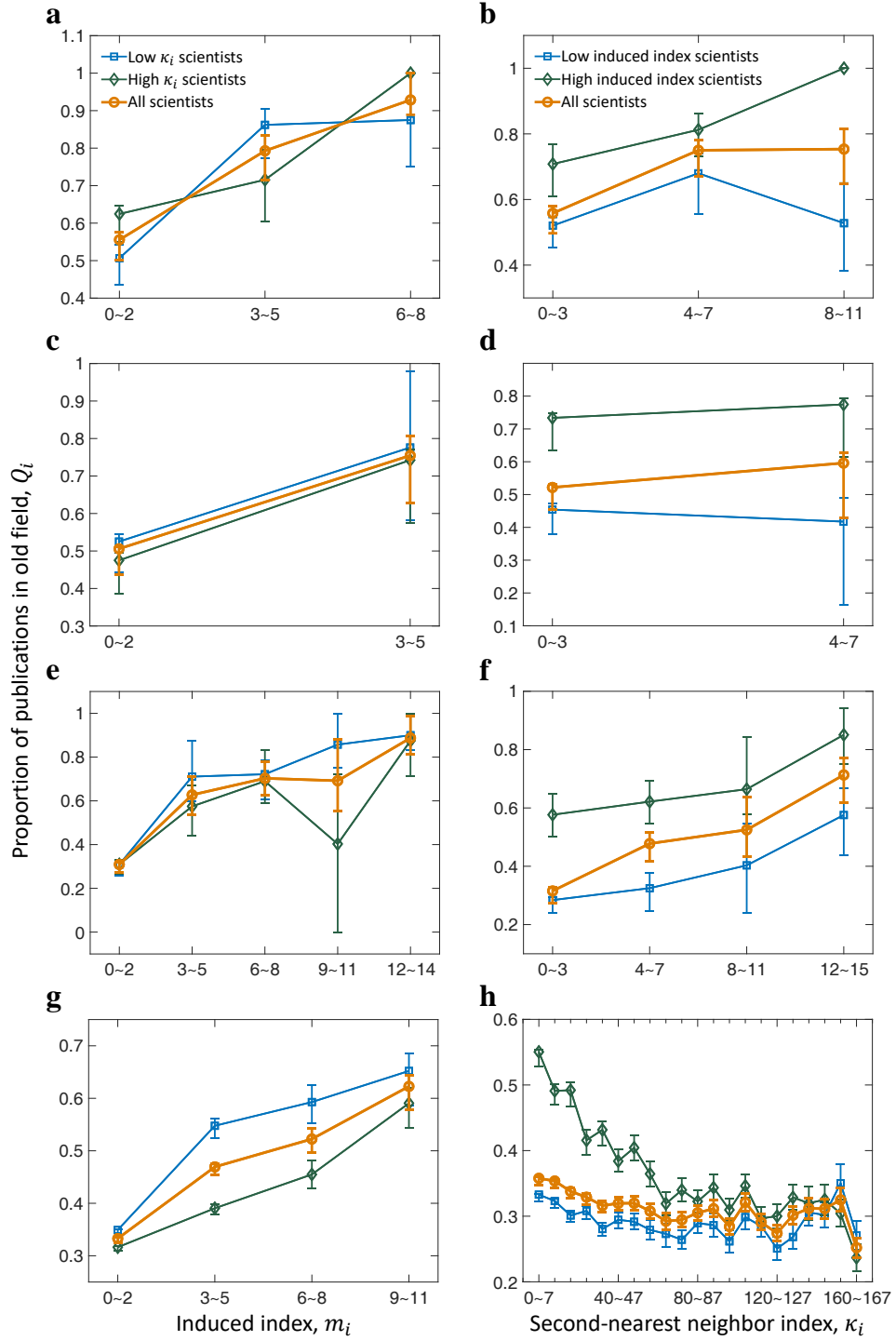


Fig. S10. Parameter robustness in comparing the induced index with the second-nearest neighbor index. Parameter settings follow the same as Fig. S8.

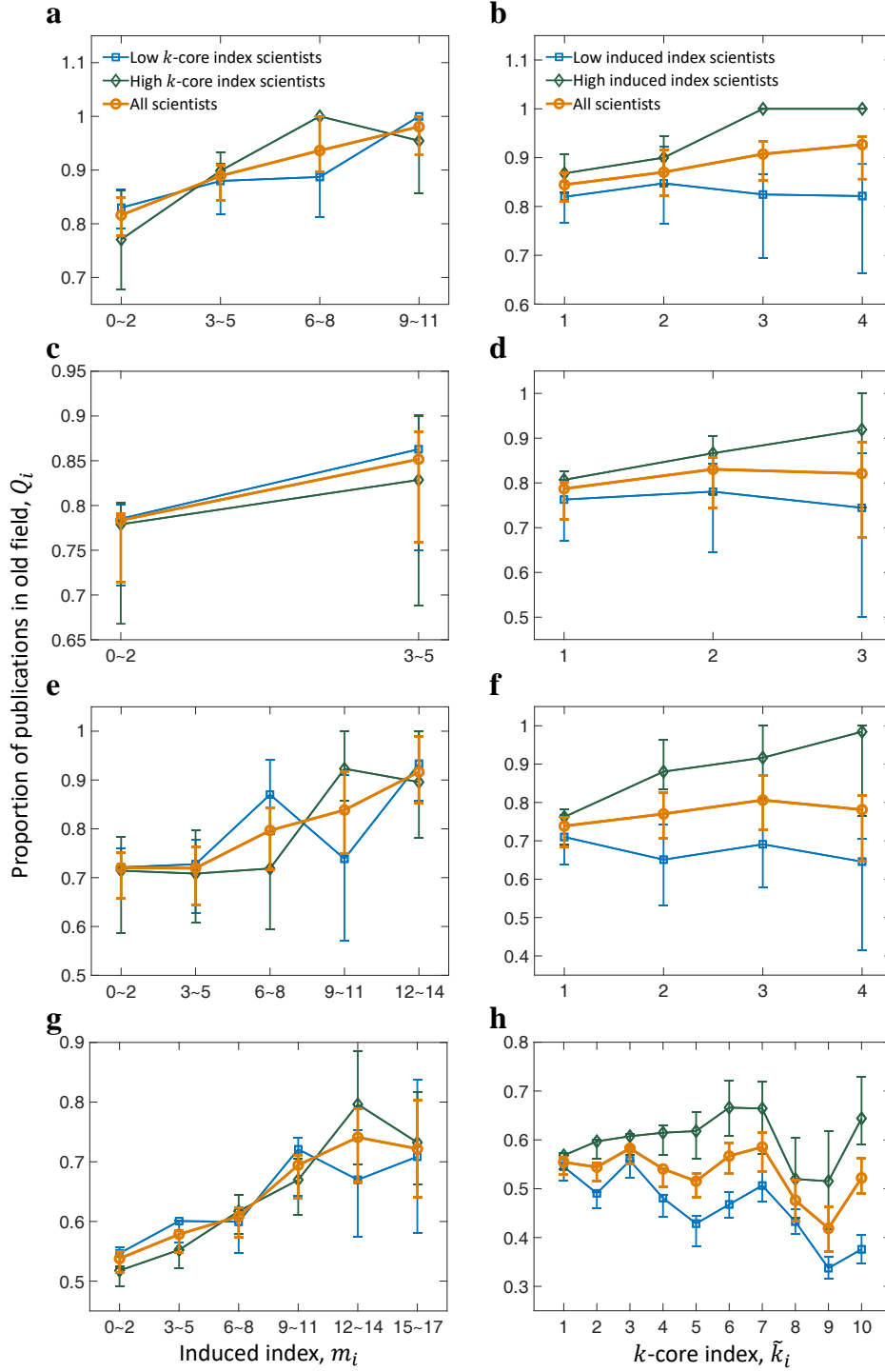


Fig. S11. Parameter robustness in comparing the induced index with the k -core index. All results are obtained by including more authors in the constructed networks: for the first three pairs, all authors that published at least 1 instead of 2 papers in 1999-2003 are included; for the fourth pair, all authors that published at least 2 instead of 5 papers in 2009-2013 are included. Remaining parameters are kept the same as in Table 1 of the Main text.

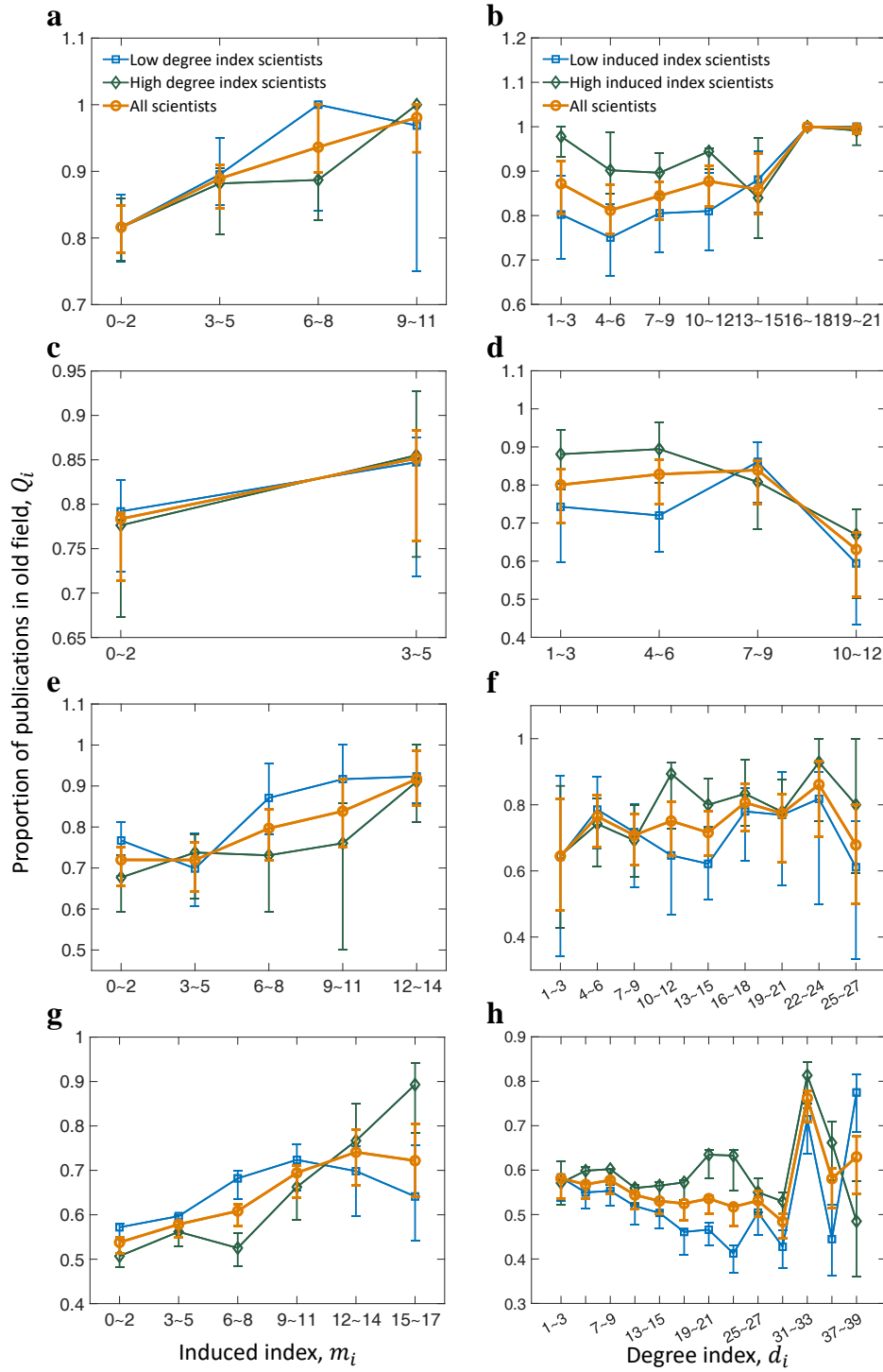


Fig. S12. Parameter robustness in comparing the induced index with the degree index. Parameter settings follow the same as Fig. S11.

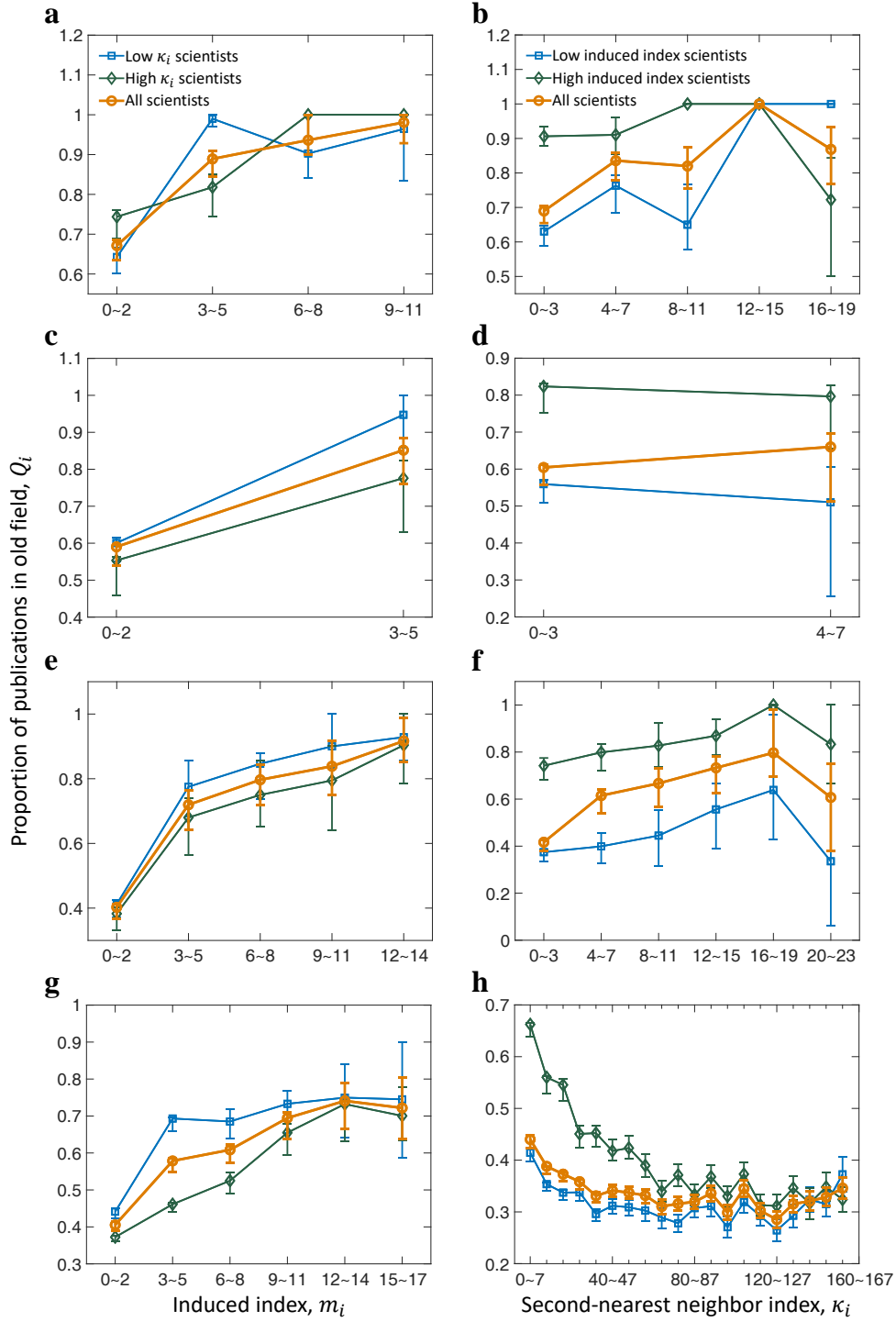


Fig. S13. Parameter robustness in comparing the induced index with the second-nearest neighbor index. Parameter settings follow the same as Fig. S11.

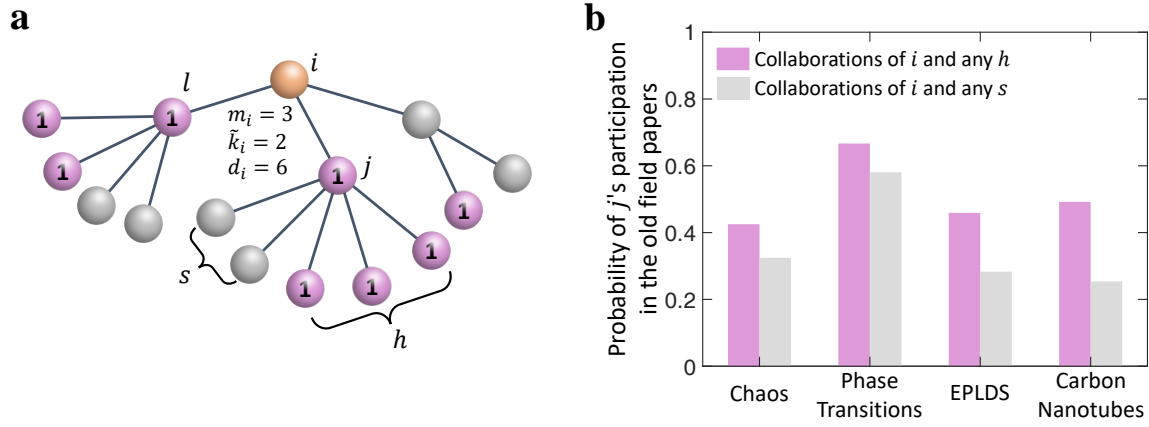


Fig. S14. More new collaborations formed due to the indirect influence mechanism. Left panel illustrates an example of a scientist i , its direct neighbor j and the second-nearest neighbors in state 1 (set h) and second-nearest neighbors in state 0 (set s). Right panel shows that among the old field publications, what are the proportions that j participates in the joint papers between i and its state-1 second-nearest neighbors h (pink bar), and the same proportion quantity for joint papers between i and its state-0 second-nearest neighbors s (gray bar). The old field publications are calculated in the observation period (2004-2006 for the first three pairs of fields and 2014-2016 for Carbon Nanotubes vs. Graphene).

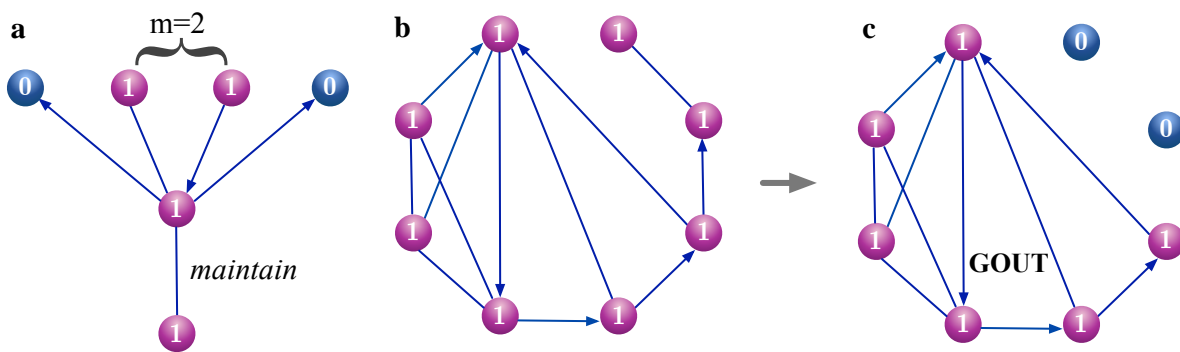


Fig. S15. Illustration of induced percolation on mixed networks.

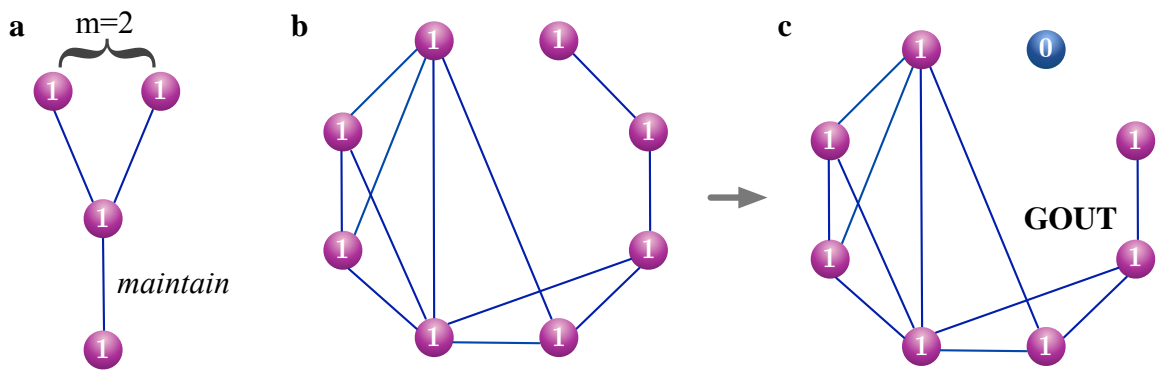


Fig. S16. Illustration of induced percolation on undirected networks.

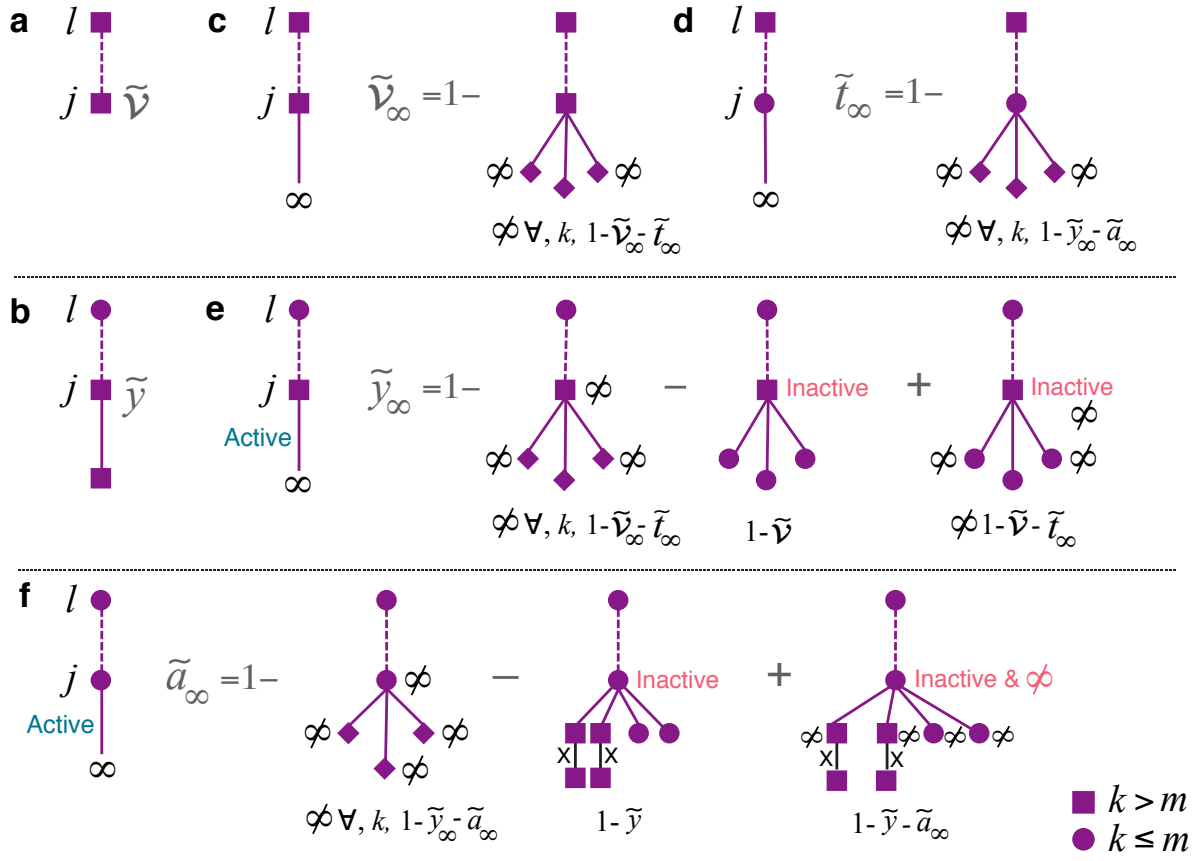


Fig. S17. Graphical illustration of conditional probabilities and their calculations for induced percolation on undirected networks.

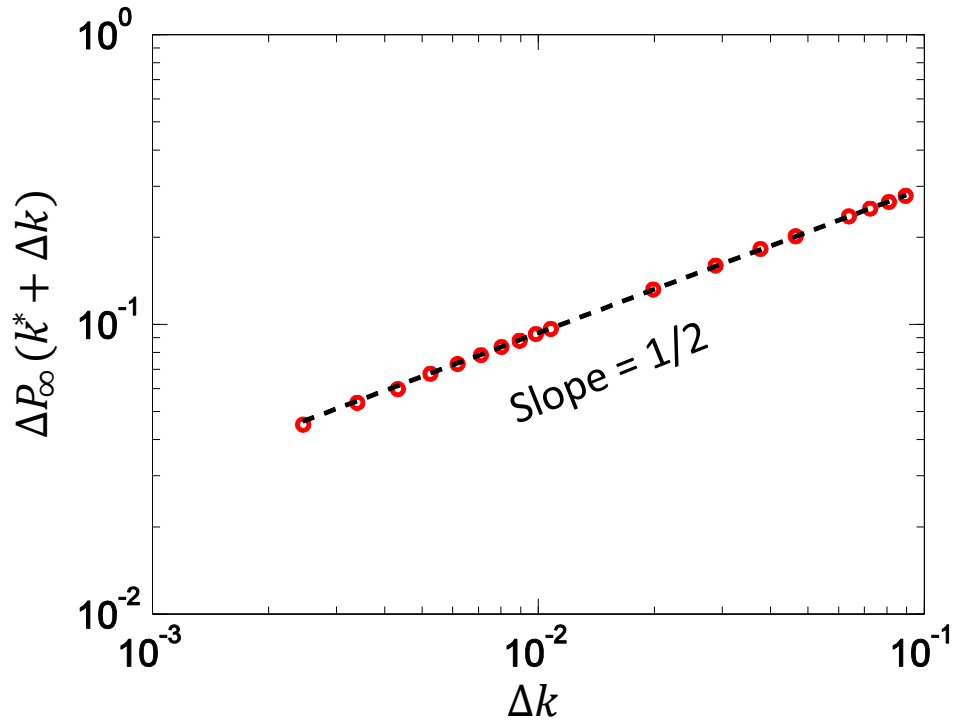


Fig. S18. Scaling behavior of ΔP_∞ as a function of $\Delta k = \langle k \rangle - k^*$ when approaching the critical point from above. The induced percolation is performed on mixed networks.

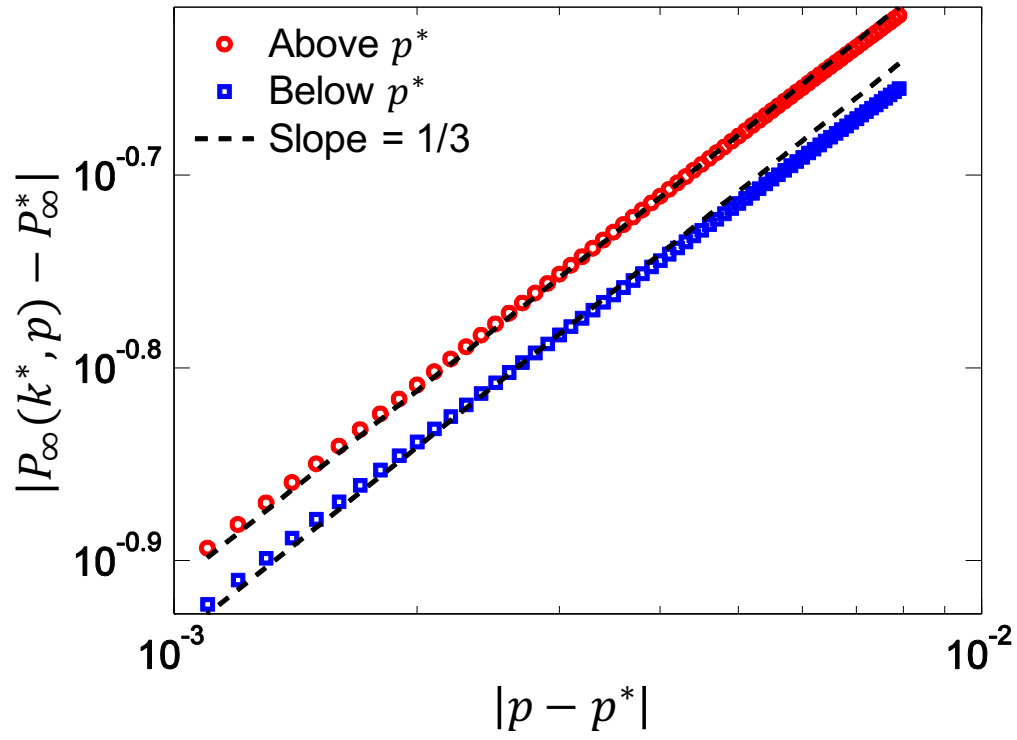


Fig. S19. The change of P_∞ near the critical point p^* as a function of $\Delta p = p - p^*$ when fixing $\langle k \rangle = k^*$. The induced percolation is performed on mixed networks.

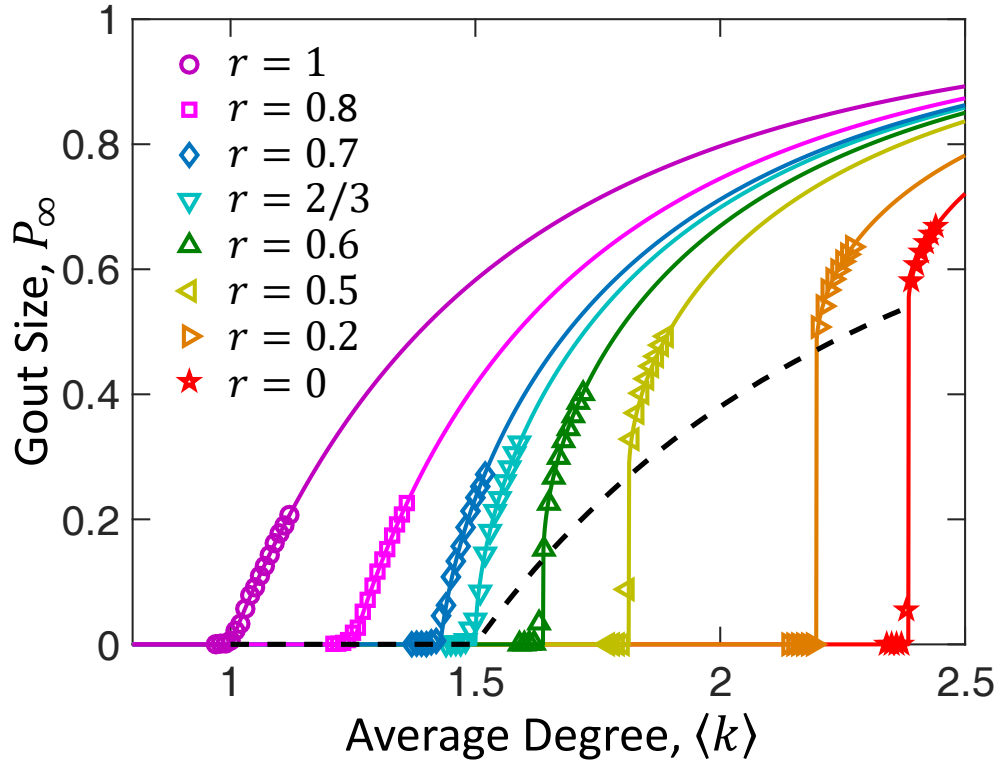


Fig. S20. Order parameter GOUT for the generalized induced probability. Markers are the numerical results using Eq. (S25) and solid lines are the corresponding theoretical predictions. For $r > 2/3$, the network undergoes a continuous phase transition, while for $r < 2/3$, the network undergoes a first order phase transition, with the height of the jump represented by the black dash line. For $r = 2/3$, the phase transition happens in $\langle k \rangle = 1.5$. The results are performed on directed ER networks.

Table S1. The description of citation networks in empirical studies.

Citation network	Num. authors N	Num. directed links M_d	Num. undirected links M_u
Chaos vs. Complex Networks	1833	11791	2676
Phase Transitions vs. Complex Networks	1265	3784	2811
EPLDS vs. OPLDS	2069	14554	3321
Carbon Nanotubes vs. Graphene	20011	168964	30729

Table S2. Definition of conditional probabilities used to derive the probability of induced percolation on mixed networks. Each row shows one conditional probability. The first column shows the notation used to denote the conditional probability that the event in the fourth column occurs for a randomly selected undirected link $\{j, l\}$ or a directed link (j, l) , given the conditional event presented in the third column. The right arrow ($j \rightarrow l$) represents that node j can keep node l active, otherwise denoted as $j \nrightarrow l$. For example, the conditional probability \tilde{v}_∞ shows the probability that given node l can keep node j active: (i) node j can keep node l active and (ii) l connects to GOUT through node j .

Conditional probability	Link type	Conditional event	Occurring event		Relation
y	Directed (j, l)	None	$j \rightarrow l$		
a			j is active but $j \nrightarrow l$		
x			j is active		$x = y + a$
\tilde{v}	Undirected $\{j, l\}$	$l \rightarrow j$	$j \rightarrow l$		
\tilde{y}		$l \nrightarrow j$	$j \rightarrow l$		
\tilde{a}		$l \nrightarrow j$	j is active but $j \nrightarrow l$		
\tilde{x}		$l \nrightarrow j$	j is active		$\tilde{x} = \tilde{y} + \tilde{a}$
y_∞	Directed (j, l)	None	(i) $j \rightarrow l$	and (ii) l connects to GOUT via j	
a_∞			(i) $j \nrightarrow l$		
x_∞			(i) j is active		$x_\infty = y_\infty + a_\infty$
\tilde{t}_∞	Undirected $\{j, l\}$	$l \rightarrow j$	(i) $j \nrightarrow l$		
\tilde{v}_∞		$l \rightarrow j$	(i) $j \rightarrow l$		
\tilde{y}_∞		$l \nrightarrow j$	(i) $j \rightarrow l$		
\tilde{a}_∞		$l \nrightarrow j$	(i) $j \nrightarrow l$		
\tilde{x}_∞		$l \nrightarrow j$	(i) j is active		$\tilde{x}_\infty = \tilde{y}_\infty + \tilde{a}_\infty$

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